# JMM

## Feature selection via mixed-integer program and supervised infinite feature selection method

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Abstract. Feature selection is an important step in data preprocessing, which helps reducing the dimensionality of data and simplifying the models. This process not only reduces the computational complexity of models, but also improves their accuracy by eliminating irrelevant features and noise. The three most widely used approaches for feature selection are filter, wrapper and embedded methods. In this paper, first we review some support vector machine based Mixed-Integer Linear Programming (MILP) models and Supervised Infinite Feature Selection (Inf-FS<sub>s</sub>) method. Then, we propose three hybrid approaches based on them. The first approach involves solving the relaxed linear model of the underlying MILP model and then solving the MILP model for those features with nonzero weights, namely a smaller MILP. In the second approach, first the Inf-FS<sub>s</sub> method is applied to rank the features. Then depending on the features costs, either chooses the top features from the ranked features until budget parameter is reached or solves a knapsack problem to select cost effective features. The third approach applies the first approach to the top 20% of features ranked by Inf-FS<sub>s</sub> method. To evaluate the proposed approaches' performance, experiments are conducted on four high-dimensional benchmark datasets for fixed and random features costs. Results demonstrate that using either of the proposed approaches can significantly reduce running time of MILP models with comparable accuracies with the original MILP models.

*Keywords*: Feature selection, Mixed integer linear program, Infinite feature selection method, Feature cost. *AMS Subject Classification* : 68T09, 90C11.

## **1** Introduction

In todays rapidly evolving data landscape, feature selection plays a pivotal role in data analysis and machine learning. The primary goal of feature selection is to reduce the dimensionality of the data, enhancing model performance by retaining only the most relevant and significant features [12]. This

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process not only mitigates computational costs but also improves model accuracy and prevents overfitting. Especially in problems with a small number of samples and high dimensionality, the performance of the model significantly improves by using a small subset of features [5, 14].

Guyon et al. [9] classified feature selection techniques into three primary categories: filter methods, wrapper methods and embedded methods. Filter methods exclude poorly informative features by analyzing their statistical properties before applying a classification algorithm. Wrapper methods work alongside the learning model, examining the entire set of variables to find feature subsets based on their predictive performance. While this approach is computationally intensive, it often yields better results than filter methods. Embedded methods, belonging to the third category, perform feature selection while simultaneously building the classifier. This can be viewed as a search through both feature subsets and hypothesis spaces. Unlike wrapper methods, which rely on a separate classification algorithm, embedded methods handle both tasks within a single process. Typically, they are less computationally demanding than wrapper methods [9].

Despite the progress in feature selection techniques [4, 8], there remains a significant challenge in addressing real-world constraints such as varied feature costs and limited budgets. Cost considerations are essential for making sensible and effective decisions in many real-world applications. Ignoring the cost factor in the feature selection process can lead to significantly undesirable outcomes. By incorporating a budget constraint, the process ensures the selection of the most informative yet cost-effective features, while preserving classification accuracy within a predefined budget. This makes the feature selection process more practical and efficient for real-world use [12]. Support Vector Machine (SVM) based feature selection approaches incorporate cost-effective feature selection in the original SVM-based models using zero-one variables. For example, Maldonado et al. [13] introduced two Mixed-Integer Linear Programming (MILP) models based on the  $L_1$ -SVM model [3] and the LP-SVM model [16], called MILP1 and MILP2, respectively, to address feature selection with budget constraints. Then, Labbe et al. [11], based on the idea introduced by Maldonado et al., proposed an extension of  $L_1$ -SVM based feature selection was proposed by Lee et al. [12] called group feature selection. They further studied its robust counterpart under uncertainty.

An issue with MILP models is that as the dimensionality increases, the time required to solve these models grows significantly. Therefore, proposing methods that reduce computational time without reducing accuracy becomes crucial. In this paper, we propose three hybrid approaches, two of which are aimed at reducing the computational time of MILP models while maintaining high accuracy. In the first approach, firstly the linear programming relaxation of the MILP model is solved. Then those features with nonzero weights are chosen and the original MILP model is applied with these less number of features. This approach is particularly advantageous for high-dimensional data, offering a reduction in computational burden without substantially impacting model accuracy. In the second approach, firstly the supervised Infinite Feature Selection (Inf-FS<sub>s</sub>) [15] is applied to rank the features using three criterion, namely Fisher score, mutual information and standard deviation. As Inf-FS<sub>s</sub> do not take into account features' costs, we either choose the first *B* features, where *B* is the budget on the features' costs or we solve a knapsack problem to select cost effective features. The third approach applies the first approach to the MILP models, restricted to the top 20% of features ranked by Inf-FS<sub>s</sub> method.

The remainder of the paper is structured as follows. In Section 2, we review two MILP feature selection models with budget constraint and the Inf-FS<sub>s</sub> method. In Section 3, we introduce the proposed approaches. Finally, in Section 4, we compare the computational time and accuracy of the proposed approaches with the MILP models discussed in Section 2.

Feature selection via MIP and Inf-FS<sub>s</sub>

## 2 MILP models and $Inf-FS_s$ method for feature selection

In this section, first we present two embedded-based MILP models for feature selection with the budget constraint. Then we present the filter-based  $Inf-FS_s$  method that ranks features based on Fisher score, mutual information and standard deviation while not taking into account features' costs.

#### 2.1 MILP models

The first MILP model, which we call MILP1, is introduced by Maldonado et al. [13] as follows:

$$\min_{w,v,b,\varepsilon} \sum_{i=1}^{m} \varepsilon_{i}$$
s.t.  $y_{i}(w^{T}x_{i}+b) \geq 1-\varepsilon_{i}, \quad i=1,\ldots,m,$   
 $l_{j}v_{j} \leq w_{j} \leq u_{j}v_{j}, \quad j=1,\ldots,n,$   
 $\sum_{j=1}^{n} c_{j}v_{j} \leq B,$   
 $v_{j} \in \{0,1\}, \quad j=1,\ldots,n,$   
 $\varepsilon_{i} \geq 0, \quad i=1,\ldots,m,$ 

$$(1)$$

where  $c_j$  is the cost of the *j*th feature, the second set of constraints bounds the features' weights, and the third constraint ensures that the total cost of the selected features does not exceed the predefined budget, *B*. If all  $c_j$ s are set to one, the budget parameter *B* represents the maximum number of selected features. If  $v_j = 0$ , then from the second set of constraints  $w_j = 0$  that means *j*th feature is not selected. Otherwise its weight is bounded below by  $l_j$  and above by  $u_j$ .

The second MILP model, which we call MILP2, is introduced by Labbe et al. [11] as follows:

$$\min_{v,w^{+},w^{-},b,\varepsilon} \sum_{j=1}^{n} (w_{j}^{+} + w_{j}^{-}) + C \sum_{i=1}^{m} \varepsilon_{i}$$
s.t.  $y_{i} \left( \sum_{j=1}^{n} (w_{j}^{+} - w_{j}^{-}) x_{ij} + b \right) \ge 1 - \varepsilon_{i}, \quad i = 1, ..., m,$   
 $w_{j}^{+} \le u_{j} v_{j}, \quad j = 1, ..., n,$   
 $w_{j}^{-} \le -l_{j} v_{j}, \quad j = 1, ..., n,$   
 $\sum_{j=1}^{n} c_{j} v_{j} \le B,$   
 $v_{j} \in \{0, 1\}, \quad j = 1, ..., n,$   
 $\varepsilon_{i} \ge 0, \quad i = 1, ..., n,$   
 $w_{j}^{+} \ge 0, \quad i = 1, ..., n,$   
 $w_{j}^{-} \ge 0, \quad i = 1, ..., n,$ 

where the parameter C in the objective function reflects the penalty for errors. It uses the decomposition of w into  $w^+$  and  $w^-$  for linearization. This formulation seeks an optimal balance between deviations and the margin. As can be observed, the second and third sets of constraints bound the features' weights and the fourth constraint is the budget constraint on features. Similar to MILP1, If  $v_j = 0$ , then from the second and third sets of constraints  $w_j = 0$  that means *j*-th feature is not selected. Their experiments showed that choosing very conservative big values for  $u_j$  and  $l_j$  for all j = 1, ..., n might lead to high computational costs. Therefore, they proposed two strategies for tightening  $u_j$  and  $l_j$  values to reach better computational results [11].

#### 2.2 Inf-FS<sub>s</sub> method

Inf-FS<sub>s</sub> is a filter-based feature selection models, which was introduced by G. Roffo et al. [15]. This method uses three criteria to calculate the score of each feature: Fisher score  $(h_i)$ , mutual information  $(m_i)$ , and standard deviation  $(\sigma_i)$ . In this approach, a complete graph G = (V, E) is constructed where nodes represent features and edges indicate the relationship between them. Each edge A(i, j) shows the probability of selecting features  $v_i$  and  $v_j$ . The Inf-FS<sub>s</sub> algorithm works by selecting features from a set of features  $F = \{f_1, \ldots, f_n\}$ , where G represents the set of classes (labels) and  $Y \in \{1, \ldots, G\}$  are the class labels. The algorithm proceeds as follows:

Algorithm 1 Supervised Infinite Feature Selection Algorithm

**Input:** Set of features  $F = \{f_1, \dots, f_n\}$ , class labels *Y*, and coefficients  $\alpha_1, \alpha_2, \alpha_3$ . **Output:** Final ranking  $\hat{C}$  for each feature.

**1. For** each i = 1, ..., n

Compute:

$$h_{i} = \frac{|\mu_{i,1} - \mu_{i,2}|^{2}}{\sigma_{i,1}^{2} + \sigma_{i,2}^{2}}, \quad m_{i} = \sum_{y \in Y} \sum_{z \in F_{i}} p(z, y) \log\left(\frac{p(z, y)}{p(z)p(y)}\right)$$

where  $\mu_{i,1}, \mu_{i,2}$  are the means for each class, and  $\sigma_{i,1}, \sigma_{i,2}$  are the standard deviations for each class. Compute the score for each feature as:

$$s_i = \alpha_1 h_i + \alpha_2 m_i + \alpha_3 \sigma_i.$$

**2.** For each i = 1, ..., n and j = 1, ..., n Set:

$$A(i,j) = s_i s_j.$$

3. Compute *r* as:

$$r=\frac{0.9}{\rho(A)},$$

where  $\rho(A)$  is the spectral radius of matrix A.

**4.** Compute the final score  $\hat{C}$  as:

$$\hat{C} = \left( (I - rA)^{-1} - I \right) e,$$

where I is the identity matrix and e is the vector of ones.

Note that the coefficients  $\alpha_1$ ,  $\alpha_2$  and  $\alpha_3$  take values between 0 and 1 with sum equals 1 that are determined using cross-validation.

Feature selection via MIP and Inf-FS<sub>s</sub>

## **3** Proposed approaches

In this section, we introduce simple hybrid approaches for the feature selection problem taking into account budget constraints on the features' costs.

• Approach 1: Consider MILP1 model (1). First we solve its relaxed model as follows:

$$\begin{array}{ll}
\min_{w,v,b,\varepsilon} & \sum_{i=1}^{m} \varepsilon_{i} \\
\text{s.t.} & y_{i}(w^{T}x_{i}+b) \geq 1-\varepsilon_{i}, \quad i=1,\ldots,m, \\
& l_{j}v_{j} \leq w_{j} \leq u_{j}v_{j}, \quad j=1,\ldots,n, \\
& \sum_{j=1}^{n} c_{j}v_{j} \leq B, \\
& 0 \leq v_{j} \leq 1, \quad j=1,\ldots,n, \\
& \varepsilon_{i} \geq 0, \quad i=1,\ldots,m.
\end{array}$$
(3)

The solution to this problem is typically sparse. Therefore, we choose features with nonzero weights (for instance  $|w_j| > 10^{-6}$ ) and solve MILP1 model only for these features, namely an MILP model with less zero-one variables. Let  $P = \{j | |w_j| > 10^{-6}\}$ , then the following MILP is solved:

$$\begin{array}{ll} \min_{w,v,b,\varepsilon} & \sum_{i=1}^{m} \varepsilon_{i} \\ \text{s.t.} & y_{i}(w^{T}x_{i}+b) \geq 1-\varepsilon_{i}, \quad i=1,\ldots,m, \\ & l_{j}v_{j} \leq w_{j} \leq u_{j}v_{j}, \quad j \in P \\ & \sum_{j \in P} c_{j}v_{j} \leq B, \\ & v_{j} \in \{0,1\}, \quad j \in P \\ & \varepsilon_{i} \geq 0, \quad i=1,\ldots,m. \end{array}$$

$$(4)$$

Since the cardinality of P is much smaller than n, MILP (4) is usually solved faster than the original MILP1. Similarly, we can apply this approach to the MILP2.

• Approach 2: First, using Inf-FS<sub>s</sub> method features are ranked. If costs are all equal to one, then we just choose the first *B* features from the ranked features. However, if features costs are different, we solve the following knapsack problem to select cost effective features:

$$\max_{x} \sum_{i=1}^{n} s_{i}x_{i}$$
  
s.t. 
$$\sum_{i=1}^{n} c_{i}x_{i} \leq B$$
  
$$x_{i} \in \{0,1\}, \quad i = 1, \dots, n$$
 (5)

where  $s_i$  and  $c_i$  are the score and cost of the *i*th feature, respectively.

• Approach 3: In this approach, we first apply  $Inf-FS_s$  to rank the features. Then we apply Approach 1 to the original MILP models, restricted to the top 20% of features ranked by  $Inf-FS_s$  method.

## **4** Experimental results

In this section, the proposed approaches in Section 3 are evaluated on four datasets and their results are compared with the original MILP models and Inf-FS<sub>s</sub> method in terms of CPU time and accuracy. All implementations are carried out on MATLAB. The optimization problems are formulated using CVX and solved using the CPLEX solver [6]. Table 1 shows the abbreviations in this section.

Abbreviation	Description
MILP1*	Application of Approach 1 to MILP1
MILP2*	Application of Approach 1 to MILP2
MILP1 <sup>*</sup>	Application of Approach 3 to MILP1
MILP2 <sup>*</sup>	Application of Approach 3 to MILP2
K-Inf-FS <sub>s</sub>	Model (5)
В	Budget parameter
$F_C \cap F_D$	The intersection of the selected features by approaches C and D

Table 1: List of abbreviations.

Furthermore, in order to evaluate the accuracy, a 10-fold cross-validation method is used, where the dataset is split into 10 equal folds [5]. The model is trained on nine of these folds, while the remaining fold (test set) is used to evaluate the model's prediction error. This procedure is repeated for all 10 folds. Accuracy is calculated as the ratio of correctly classified samples to the total number of samples in the testing set and is defined as:

$$Accuracy = \frac{TP + TN}{TP + TN + FP + FN}$$

In this formula,

- TP (True Positives) refers to the number of positive samples correctly classified,
- TN (True Negatives) refers to the number of negative samples correctly classified,
- FP (False Positives) refers to the number of negative samples incorrectly classified as positive, and
- FN (False Negatives) refers to the number of positive samples incorrectly classified as negative.

#### 4.1 Datasets and parameters setting

Table 2 shows the datasets information, where *m* and *n* represent the number of samples and the number of features, respectively. Using an appropriate penalty parameter affects the accuracy of the model. For each dataset, penalty parameters from the  $\{2^{-7}, 2^{-6}, \dots, 2^{-1}, 2^0, 2^1, \dots, 2^6, 2^7\}$  are considered, and the best one is selected based on accuracy that are given in Table 3. It should be noted that the MILP1 model does not have a penalty parameter. Furthermore, the  $\alpha$  parameters ( $\alpha_1$ ,  $\alpha_2$ , and  $\alpha_3$ ) that are most suitable for the Inf-FS<sub>s</sub> model are presented in Table 4. These values are determined through cross-validation.

#### 4.2 Equal features costs

In the first scenario, the cost of each feature is considered fixed and equal to one. Moreover, to evaluate the model's performance under different budget parameter, the values 10, 20, and 30 are assigned to the

 Table 2: Datasets information.

DATASETS	$m \times n$
COLONCANCER [1]	$62 \times 2000$
LYMPHOMA [7]	$45 \times 4026$
LEUKEMIA [7]	$72 \times 7070$
PROSTATE [2]	$102 \times 6033$

**Table 3:** The best penalty parameter (C) used for the datasets in each model.

DATASET	MILP1	MILP2	Inf-FS <sub>s</sub>
COLONCANCER	-	$2^{0}$	$2^{-4}$
LYMPHOMA	-	2 <sup>5</sup>	20
LEUKEMIA	-	2 <sup>5</sup>	27
PROSTATE	-	$2^{-1}$	$2^{-7}$

**Table 4:** The  $\alpha$  parameters in the Inf-FS<sub>s</sub> method.

DATASET	COLONCANCER	LYMPHOMA	LEUKEMIA	PROSTATE
$\alpha_1$	0.8	0.5	0.9	0.6
$\alpha_2$	0.1	0.2	0	0.1
α <sub>3</sub>	0.1	0.3	0.1	0.3

budget parameter (B). The best results in terms of accuracy and execution time for each budget parameter are bold numbers in the tables and the second best result is marked with a superscript "\*".

Model		B=10	B=20	B=30
MIL D1	Accuracy	88.6	88.8	85.7
WIILFI	Time	11.2	10000	10000
MILD1*	Accuracy	88.8*	88.3	85.1
IVIILF I	Time	9.7*	860	10000
	Accuracy	88.6	90.5	87.6*
WIILF 2	Time	21.3	10000	10000
MIL D2*	Accuracy	88.8*	90.5	86.7
WIILF 2	Time	10	942	10000
Inf-FS <sub>s</sub>	Accuracy	87.5	80	82.2
	Time	7.8	7.9	7.8
MIL D1*	Accuracy	90	88.6	87.1
WIILP1 <sub>s</sub>	Time	12.8	57.5*	1920.7*
MIL D2*	Accuracy	88.8*	89	88.6
$MILP2_s^*$	Time	12.6	67	2137.7

Table 5: Time and accuracy comparison for COLONCANCER dataset.

For the COLONCANCER dataset, one can see from Table 5 that the Inf-FS<sub>s</sub> model is the fastest in terms of execution time across all budget scenarios. For B = 10, Approach 1 reduces the running times of MILP1 and MILP2 models. For B = 20, Approaches 1 and 3 both significantly reduces the running times of the models. In the case of B = 30, just Approach 3 reduces the running times of the original MILP models. From the accuracy point of view, Inf-FS<sub>s</sub> exhibits the worst accuracy among all models and we see no significant differences between the MILP models and the proposed approaches. In the case of B = 30, MILP1<sup>\*</sup><sub>s</sub> and MILP2<sup>\*</sup><sub>s</sub> have the highest accuracy, while for the case B = 20, MILP2 and MILP2<sup>\*</sup> have jointly the highest accuracy.

В	10	20	30
$F_{MILP1} \cap F_{MILP1^*}$	77.3	83.6	72.4
$F_{MILP2} \cap F_{MILP2^*}$	100	74	81.9
$F_{MILP1^*} \cap F_{MILP2^*}$	72.7	80*	75.5
$F_{MILP1^*} \cap F_{Inf\text{-}FS_s}$	80	60	50
$F_{MILP2^*} \cap F_{Inf\text{-}FS_s}$	100	50	40
$F_{MILP1_s^*} \cap F_{MILP1}$	72.8	76.5	66.5
$F_{MILP2_s^*} \cap F_{MILP2}$	92.2*	68.2	74.6
$F_{MILP1_s^*} \cap F_{MILP2_s^*}$	72.7	80*	77.1*
$F_{MILP1_s^*} \cap F_{Inf-FS_s}$	70	50	45
$F_{MILP2_s^*} \cap F_{Inf\text{-}FS_s}$	70	40	42

 Table 6: Features overlap percentage on COLONCANCER dataset.

We also report features' overlap between all methods in Table 6 for the COLONCANCER dataset. As we see, the proposed Approaches 1 and 3 have high overlap with the original MILP models. Furthermore, in cases of B = 20 and 30 one can see that features overlap between MILP models and Inf-FS<sub>s</sub> is the worst, that might be due to the fact that they belong to different features selection methods (embedded and filter methods). Moreover, as expected MILP models have more features in common with Approach 1 than with Approach 3.

Model		B=10	B=20	B = 30
MIL D1	Accuracy	93.3	91.5	91.7
	Time	51	10000	60
MIL D1*	Accuracy	93.3	93.3*	95.8*
	Time	26*	66.8	25.8
	Accuracy	94.5*	91.8	89.5
WIILF 2	Time	70	10000	18.3*
MIL D2*	Accuracy	93.8	92.5	90
	Time	20.8	37.3	7.2
Inf-FS <sub>s</sub>	Accuracy	95.8	100	98.5
	Time	40.3	45*	45
MIL D1*	Accuracy	93.5	92	95.5
	Time	62.2	74	63.1
MIL D2*	Accuracy	92.5	91.8	90.5
$ MILP2_s $	Time	61.4	70.2	62

Table 7: Time and accuracy comparison for LYMPHOMA dataset.

The results for the LYMPHOMA dataset are reported in Tables 7 and 8. The reduction in execution time in the Approach 1 compared to the original MILP models is evident for all budget scenarios. Approach 3 for the case of B = 10 reduces the running time of MILP2. In case of B = 20, Approach 3 reduces the running times of MILP models. From the accuracy point of view, Inf-FS<sub>s</sub> has the best accuracy for all budget scenarios.

According to the features' overlap between all methods in Table 8 for the LYMPHOMA dataset, one

В	10	20	30
$F_{MILP1} \cap F_{MILP1^*}$	89.5	78.8	61.8
$F_{MILP2} \cap F_{MILP2^*}$	94.7	91.1	81
$F_{MILP1^*} \cap F_{MILP2^*}$	84.2	84.6	63.1
$F_{MILP1^*} \cap F_{Inf-FS_s}$	50	50	56.6
$F_{MILP2^*} \cap F_{Inf\text{-}FS_s}$	40	50	46.6
$F_{MILP1_s^*} \cap F_{MILP1}$	84.2	73.6	56
$F_{MILP2_{s}^{*}} \cap F_{MILP2}$	89.1	86.6	76.6
$F_{\text{MILP1}_{s}^{*}} \cap F_{\text{MILP2}_{s}^{*}}$	94.4*	86.8*	71.2*
$F_{\text{MILP1}_s^*} \cap F_{\text{Inf-FS}_s}$	70	50	70
$F_{MILP2_s^*} \cap F_{Inf-FS_s}$	60	50	63.3

Table 8: Features overlap percentage on LYMPHOMA dataset.

can see that the proposed approaches have high overlap with the original MILP models.

Model		B=10	B = 20	B=30
MIL D1	Accuracy	96.9	94.6	97.3
	Time	6820	252	119
MIL D1*	Accuracy	95.2	98.5*	96.8
	Time	40	25.8	23.8
MIL D2	Accuracy	97.6	97.3	97
WIILF 2	Time	10000	10000	2312
MIL D2*	Accuracy	96.1	98.8	97
	Time	49.1*	1973	38.1*
Inf-FS <sub>s</sub>	Accuracy	97.3*	98.8	100
	Time	137	150*	150.5
MIL D1*	Accuracy	96.3	97.2	97.8*
MILPIs	Time	197.5	193.8	190.2
MILP2 <sup>*</sup>	Accuracy	97.1	98.8	94.4
	Time	200.5	356	198

Table 9: Time and accuracy comparison for LEUKEMIA dataset.

The results for LEUKEMIA dataset are summarized in Tables 9 and 10. The reduction in execution times in the Approaches 1 and 3 compared to the original MILP models is evident. According to the Table 9, the best running times for all budget scenarios correspond to the MILP1\* model. From the accuracy point of view, MILP2 has the best accuracy for the case B = 10, while in the case of B = 20 three approaches jointly have the best accuracy. As can be seen for the case of B = 30, Inf-FS<sub>s</sub> has the best accuracy.

Features overlap between all methods in Table 10 for the LEUKEMIA dataset show that the proposed Approaches 1 and 3 have high overlap with the original MILP models in most cases.

The results for PROSTATE dataset are reported in Tables 11 and 12. Except the case B = 10, for the other two budgets Inf-FS<sub>s</sub> has the worst accuracy. The best accuracy for the first two budget scenarios correspond to MILP1\* and for the case B = 30 belongs to MILP1. Also, one can observe that the

В	10	20	30
$F_{MILP1} \cap F_{MILP1^*}$	88.5	55	45
$F_{MILP2} \cap F_{MILP2^*}$	87.5	86.4*	96*
$F_{MILP1^*} \cap F_{MILP2^*}$	88.5	58.5	53
$F_{MILP1^*} \cap F_{Inf\text{-}FS_s}$	90*	60	66.6
$F_{MILP2^*} \cap F_{Inf-FS_s}$	100	60	66.6
$F_{MILP1_s^*} \cap F_{MILP1}$	76.4	46	39.6
$F_{MILP2_s^*} \cap F_{MILP2}$	76.6	73.3	85.2
$F_{\text{MILP1}_{s}^{*}} \cap F_{\text{MILP2}_{s}^{*}}$	87	95.5	99
$F_{MILP1_s^*} \cap F_{Inf-FS_s}$	70	70	56.7
$F_{MILP2_s^*} \cap F_{Inf-FS_s}$	80	70	63.3

Table 10: Features overlap percentage on LEUKEMIA dataset.

**Table 11:** Time and accuracy comparison for PROSTATE dataset.

Model		B = 10	B=20	B=30
MIL D1	Accuracy	90.6	91.2	94.1
WIILF I	Time	197.2	351.6	10000
MII D1*	Accuracy	91.2	92.5	93.4*
WIILF I	Time	102	118.5	767.5
MIL D2	Accuracy	90.7*	91.2	93.1
MILP2	Time	137.4	184.7	10000
MIL D2*	Accuracy	90.7*	91.2	93.1
WIILF 2	Time	30.3	34	593
Inf ES	Accuracy	90.3	86	87.2
IIII-1'5 <sub>s</sub>	Time	84*	85*	84.2
MIL D1*	Accuracy	90.3	92.3*	93.4*
MILP1 <sub>s</sub>	Time	113.2	120.6	136.2*
MIL D2*	Accuracy	90.2	91.2	93.2
$\text{MILP2}_{s}^{+}$	Time	112.6	125.8	139.1

proposed Approaches 1 and 3 perform faster compared to the original MILP models. The Inf-FS<sub>s</sub> is the fastest for B = 30 in Table 11. According to the Table 11, the best running times for the first two budget parameters correspond to MILP2\*.

Finally, as before for the PROSTATE dataset one can see that the proposed Approaches 1 and 3 have again high overlap with the original MILP models.

#### 4.3 Random features costs

In the second scenario, the cost of selecting each feature is randomly determined between 1 and 10. To evaluate the models' performance under different budget conditions, the values of 10, 20, 30, and 50 are considered for the budget parameter (B). Computational results are summarized in Tables 13-20.

The results for COLONCANCER dataset are presented in Table 13. As can be seen, the reduction in execution times in the Approaches 1 and 3 compared to the original MILP models is evident for all

В	10	20	30
$F_{MILP1} \cap F_{MILP1^*}$	93.3	84.6	82.1
$F_{MILP2} \cap F_{MILP2^*}$	100	97.4	94.9
$F_{MILP1^*} \cap F_{MILP2^*}$	93.3*	86.8	82.1
$F_{MILP1^*} \cap F_{Inf-FS_s}$	60	50	43.3
$F_{MILP2^*} \cap F_{Inf-FS_s}$	60	50	50
$F_{MILP1_s^*} \cap F_{MILP1}$	91.2	82.6	78.3
$F_{MILP2_{s}^{*}} \cap F_{MILP2}$	97.8*	93.2*	87.4*
$F_{\text{MILP1}_{s}^{*}} \cap F_{\text{MILP2}_{s}^{*}}$	100	88.2	84.6
$F_{\text{MILP1}_{s}^{*}} \cap F_{\text{Inf-FS}_{s}}$	70	65	40
$F_{MILP2_s^*} \cap F_{Inf-FS_s}$	70	65	40

Table 12: Features overlap percentage on PROSTATE dataset.

Table 13: Time and accuracy comparison for COLONCANCER dataset.

Model		B = 10	B=20	B=30	B=50
MIL D1	Accuracy	84.1	87.1	88.3*	86.6
WIILF I	Time	17.1	19.5	239	10000
MII D1*	Accuracy	84	86.7	87.7	86.9
WIILF I	Time	9.5	11.8	109	6580
MIL D2	Accuracy	84	87	88.4	87.6
MILP2	Time	24.5	28.4	252	10000
MIL DO*	Accuracy	84.3*	87	88.4	87.7
WIILF 2	Time	15.2	16.1	94	7610
K-Inf-FS <sub>s</sub>	Accuracy	87.8	87	86.1	90.4
	Time	12.5*	13.1*	13.2	13.7
MILP1 <sup>*</sup>	Accuracy	83.5	87.8*	88.2	88.7
	Time	12.8	13.6	15.1*	49.4*
MILP2 <sup>*</sup> <sub>s</sub>	Accuracy	83.8	88.6	88.2	89.2*
	Time	12.5*	13.4	15.3	55.3

budget scenarios. For B = 10 and 20, MILP1\* is the fastest in terms of execution time. For B = 30 and 50, K-Inf-FS<sub>s</sub> has the best execution time. From the accuracy point of view, for B = 10, 50, K-Inf-FS<sub>s</sub> is the best, for B = 20 MILP2<sup>\*</sup> is the best and for B = 30 MILP2 and MILP2\* are jointly the bests. In general, for the budget parameter B = 10, the accuracies of the models all less than the other budget parameters.

From Table 14 for the COLONCANCER dataset, one can observe that the proposed Approaches 1 and 3 exhibit a high overlap with the original MILP models, similar to the case with fixed features costs. Also, it can be noted that features' overlap between between different methods (embedded and filter methods) is smaller compared to the case where two method belong to one class.

The results for LYMPHOMA dataset are presented in Tables 15 and 16. One can observe that the Approach 1 for all budget parameters performs faster than original MILP models. In addition, Approach 2 for budget cases B = 30 and 50 performs faster than original MILP models, while for the budget parameters B = 10 and 20 it doesnt. According to Table 15, the best running times, except for the budget

В	10	20	30	50
$F_{MILP1} \cap F_{MILP1^*}$	88.8	87.1	86	82.6
$F_{MILP2} \cap F_{MILP2^*}$	97.7	100	98.4	92
$F_{MILP1^*} \cap F_{MILP2^*}$	87.5	86.7	83.7	78.9
$F_{MILP1^*} \cap F_{K\text{-}Inf\text{-}FS_s}$	63.6	61.5	48.2	61.9
$F_{MILP2^*} \cap F_{K\text{-Inf-FS}_s}$	63.6	61.5	48.2	47.6
$F_{MILP1_s^*} \cap F_{MILP1}$	79.8	79.6	78.6	74
$F_{MILP2^*_s} \cap F_{MILP2}$	89.2	94.5	93.2*	85.5
$F_{MILP1_s^*} \cap F_{MILP2_s^*}$	92.2*	92.1*	89	88*
$F_{MILP1_s^*} \cap F_{Inf-FS_s}$	70	77.8	72.8	70.5
$F_{MILP2_s^*} \cap F_{Inf-FS_s}$	67.5	77.8	71.8	63.5

 Table 14: Features overlap percentage on COLONCANCER dataset.

Table 15: Time and accuracy comparison for LYMPHOMA dataset.

Model		B = 10	B=20	B=30	B=50
MIL D1	Accuracy	91.5*	91	94	93.4
	Time	23.5	31.4	88.2	10000
MIL D1*	Accuracy	90.5	90.3	92	93.5
	Time	15*	19.8*	22.4*	221.5
MIL D2	Accuracy	91.2	91.1	93.6	93.5
MILP2	Time	24.5	37.1	106	10000
MIL D2*	Accuracy	90.7	92*	94.4*	93.5
MILP2*	Time	12.8	15.4	21.3	206
K-Inf-FS <sub>s</sub>	Accuracy	97.5	95.6	96.2	99.2
	Time	44	44.5	45.2	45.6
MILP1 <sup>*</sup>	Accuracy	90.5	90.6	93.2	94.5
	Time	62.2	63	63.9	70.2*
MILP2 <sup>*</sup>	Accuracy	90	91	94	95.4*
	Time	61.7	62.4	62.3	76.6

parameter B = 50, correspond to MILP2<sup>\*</sup> and for the case B = 50, K-Inf-FS<sub>s</sub> has the best running time. Also, the second best running times for all parameter budgets (except B = 50) belong to MILP1<sup>\*</sup>. In terms of accuracy, K-Inf-FS<sub>s</sub> exhibits the highest accuracy for budget parameters B = 10, 20 and 30.

As before, in Table 16 one can see that the proposed Approaches 1 and 3 have high features' overlap with the original MILP models for the LYMPHOMA dataset.

The results for LEUKEMIA dataset are summarized in Tables 17 and 18. From Table 17, one can observe that for the budget parameters B = 20 and 30, Approaches 1 and 3 perform faster compared to the original MILP models. For the case B = 10, Approach 1 performs faster than the original models. For the case B = 50, Approach 1 performs faster compared to the two original MILP models and Approach 3 exhibits a better running time only compared to the MILP2 model. According to this table, the best running times for the budget parameters B = 10, 30 and 50 correspond to MILP1\*, while MILP2\* has the shortest running time for B = 20. In terms of accuracy, K-Inf-FS<sub>s</sub> and MILP2<sup>s</sup> for budget parameter B = 10 and 20 have the best accuracies, respectively. For the cases B = 30 and 50 MILP2\* has the best

В	10	20	30	50
$F_{MILP1} \cap F_{MILP1^*}$	92*	86.7	86	80.5
$F_{MILP2} \cap F_{MILP2^*}$	90.7	97.6	95.9	88.7
$F_{MILP1^*} \cap F_{MILP2^*}$	90	88	87.8	81.1
$F_{MILP1^*} \cap F_{K\text{-}Inf\text{-}FS_s}$	62.5	63.5	64.6	66.6
$F_{MILP2^*} \cap F_{K\text{-Inf-FS}_s}$	64.6	66.7	64.6	63.2
$F_{MILP1_s^*} \cap F_{MILP1}$	86	91.6*	79.2	73.6
$F_{MILP1_s^*} \cap F_{MILP1}$	87.2	79.4	88.6	79.5
$F_{MILP1_s^*} \cap F_{MILP2_s^*}$	100	88.7	93.7*	82.6*
$F_{\text{MILP1}_s^*} \cap F_{\text{Inf-FS}_s}$	69.2	76.1	74.3	68.8
$F_{MILP2_s^*} \cap F_{Inf-FS_s}$	69.2	80.4	78.6	63.2

Table 16: Features overlap percentage on LYMPHOMA dataset.

Table 17: Time and accuracy comparison for LEUKEMIA dataset.

Model		B = 10	B=20	B=30	B=50
MIL D1	Accuracy	91.1	92.6	93.6	92.6
	Time	97.6	10000	261	169.2*
MIL D1*	Accuracy	90.6	93.3	97.4*	95.1
	Time	48.8	199	88.6	44
MIL D2	Accuracy	90.9	91.6	97.1	95.3
WIILF 2	Time	163	10000	10000	10000
MIL D2*	Accuracy	91.8	92.7	97.6	97.2
	Time	81.8*	142	10000	10000
K-Inf-FS <sub>s</sub>	Accuracy	95.8	94.2	96.6	96.6*
	Time	195.3	188.9*	197.2*	196
MILP1 <sup>*</sup>	Accuracy	90.5	94.8*	96.8	93.2
	Time	192.3	216.2	200.6	205.9
MILP2 <sup>*</sup>	Accuracy	92.4*	96.5	97	95
	Time	192.6	222.6	1141	3527

#### accuracies.

According to the Table 18 for the LEUKEMIA dataset, one can see that the proposed Approaches 1 and 3 have high overlap with the original MILP models in most cases.

For the PROSTATE dataset the results are summarized in Tables 19 and 20. One can see that the proposed Approaches 1 and 3 perform faster than the original MILP models for the budget parameters B = 30 and 50. For the first two budget parameters B = 10 and 20, Approach 1 performs faster. It can also be seen from Table 19 that MILP2\* has the best running time for all budget parameters. From the accuracy point of view, one can see that K-Inf-FS<sub>s</sub> has the best accuracy for the cases B = 10 and 20, while for the budget parameters B = 30 and 50 MILP1 and MILP2\* have the best accuracies, respectively.

Finally, similar to the previous datasets, one can see that the proposed Approaches 1 and 3 have high features' overlap with the original MILP models as reported in Table 20 for the PROSTATE dataset.

В	10	20	30	50
$F_{MILP1} \cap F_{MILP1^*}$	93.8*	79.9*	68.5	47.1
$F_{MILP2} \cap F_{MILP2^*}$	100	91.3	77.5	73.6
$F_{MILP1^*} \cap F_{MILP2^*}$	87.5	75.4	52.6	32.1
$F_{MILP1^*} \cap F_{K\text{-Inf-FS}_s}$	66.7	67.1	52.2	55.9
$F_{MILP2^*} \cap F_{K\text{-Inf-FS}_s}$	66.7	65.7	69.4	50
$F_{MILP1_s^*} \cap F_{MILP1}$	83.4	70.2	59.2	36.8
$F_{MILP2_s^*} \cap F_{MILP2}$	88.2	82.6	65.7	63.2
$F_{MILP1_s^*} \cap F_{MILP2_s^*}$	85.9	75.4	73.5*	66.2
$F_{MILP1_s^*} \cap F_{Inf-FS_s}$	72.7	67.1	67.5	82.3
$F_{MILP2^*_s} \cap F_{Inf\text{-}FS_s}$	72.7	65.7	63.9	78.2*

 Table 18: Features overlap percentage on LEUKEMIA dataset.

Table 19: Time and accuracy comparison for PROSTATE dataset.

Model		B=10	B=20	B=30	B=50
MIL D1	Accuracy	85.7	85.6	89.9	92.6
IVIILF I	Time	104	134.5	204.8	431.8
MIL D1*	Accuracy	85.6	86.8*	88.7	92.8*
	Time	69	74.5	97.1	121.6
MIL D2	Accuracy	86*	85.8	89.4	92.6
MILP2	Time	44*	61.8*	126.3	417.6
MIL D2*	Accuracy	85.9	86.2	89.6*	92.9
	Time	21	22.3	24.9	46.2
K-Inf-FS <sub>s</sub>	Accuracy	90.6	87.7	86.2	87.5
	Time	93.7	85.5	95*	120.2*
MILP1 <sup>*</sup>	Accuracy	84.1	85.8	88.7	91.5
	Time	122.7	123.9	115.6	124.9
MILP2 <sup>*</sup>	Accuracy	84.2	85.3	89	92.3
	Time	111.1	111.9	113.4	122.5

## 5 Conclusions and future works

In this paper, first two MILP models for cost-effective feature selection and Inf-FS<sub>s</sub> model for feature ranking are reviewed. Then three hybrid approaches are proposed for cost effective feature selection. In the first approach, the relaxed linear version of the MILP model is solved first. Then, the MILP model for nonzero features weights ( $|w_j| > 10^{-6}$ ) is solved, namely an MILP with less 0-1 variables. Then Inf-FS<sub>s</sub> method is applied to rank the features. Then the first approach is applied to the original MILP models, restricted to the top 20% of features ranked by Inf-FS<sub>s</sub> method. The most important characteristic of the proposed approaches is that they are faster in terms of running time compared to the original MILP models, while they share most of the selected features.

As a continuation of this research, the following suggestions can be considered as potential future research directions:

В	10	20	30	50
$F_{MILP1} \cap F_{MILP1^*}$	93.2*	93.3*	88.4	84.3*
$F_{MILP2} \cap F_{MILP2^*}$	93.8	97.1	89.5*	84.1
$F_{MILP1^*} \cap F_{MILP2^*}$	91.5	89.2	87	82.6
$F_{MILP1^*} \cap F_{K\text{-}Inf\text{-}FS_s}$	33.3	63.5	60.5	56.1
$F_{MILP2^*} \cap F_{K\text{-Inf-FS}_s}$	33.3	63.5	58	56.8
$F_{MILP1_s^*} \cap F_{MILP1}$	92.4	91.2	83.6	79.2
$F_{MILP2_s^*} \cap F_{MILP2}$	90.2	94.6*	84.4	78.2
$F_{MILP1_s^*} \cap F_{MILP2_s^*}$	89.8	84	90.8	85.8
$F_{MILP1_s^*} \cap F_{Inf-FS_s}$	61.9	75.9	77.3	60.8
$F_{MILP2^*_s} \cap F_{Inf\text{-}FS_s}$	61.9	75.9	78.8	62.7

Table 20: Features overlap percentage on PROSTATE dataset.

- Incorporating budget constraints into the structure of the Inf-FS<sub>s</sub> method.
- Investigating and evaluating the robustness of the proposed approaches against data uncertainty.
- Exploring and testing the proposed approaches for nonlinear separation problems.
- Combining the proposed approaches with the clustering  $Inf-FS_s$  method proposed in [10].

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