

A nonlocal Cauchy problem for nonlinear fractional integro-differential equations with positive constant coefficient

Shivaji Ramchandra Tate^{†*}, Vinod Vijaykumar Kharat[‡]
and Hambirrao Tatyasaheb Dinde[§]

[†]*Department of Mathematics, Kisan Veer Mahavidyalaya, Wai, India*

[‡]*Department of Mathematics, N.B. Navale Sinhgad College of Engg.,
Solapur, India*

[§]*Department of Mathematics, Karmaveer Bhaurao Patil College,
Urun-Islampur, India*

Emails: tateshivaji@gmail.com, vkvinod9@gmail.com, drhtdmaths@gmail.com

Abstract. In this paper, we study the existence, uniqueness and stability of solutions of a nonlocal Cauchy problem for nonlinear fractional integro-differential equations with positive constant coefficient. The results heavily depend on the Banach contraction principle, Schaefer's fixed point theorem and Pachpatte's integral inequality. In the last, results are illustrated with suitable example.

Keywords: Fractional integro-differential equation, Existence of solution, Fixed point, Pachpatte's integral inequality, Stability.

AMS Subject Classification: 26A33, 45J05, 34K10, 45M10.

1 Introduction

The idea of fractional differentiation was introduced by Riemann and Liouville in the nineteenth century. It is the generalization of ordinary differentiation and integration to arbitrary non-integer order, for details, see [1, 2, 6, 8, 9, 30, 32] and the references therein.

*Corresponding author.

Received: 5 November 2018 / Revised: 17 January 2019 / Accepted: 21 January 2019.

DOI: 10.22124/jmm.2019.11580.1199

The area of fractional differential equations is now considered to be very important due to its various applications in different fields of science and technology such as control theory, rheology, signal processing, modelling, fractals, chaotic dynamics, bioengineering and biomedical and so on, for example see [9, 24, 37] and the references therein. Recently, many researchers studied the fractional differential and integro-differential equations and obtained many interesting existence and uniqueness results, see [4, 11, 23, 38].

The stability problem of functional equations was introduced by Ulam [39, 40] and Hyers [18] which is known as Hyers-Ulam stability. Rassias [33] studied the Hyers-Ulam stability of linear and nonlinear mapping. Jung [19, 20] established Hyers-Ulam stability for more general mapping on restricted domain. Obloza [29] was the first who studied the Hyers-Ulam stability of linear differential equations. Later many researchers studied the Ulam type stability, for detail see [3, 5, 7, 15–17, 21, 22, 26, 33–36, 41–43].

In [14], Castro and Simões studied different kinds of Hyers-Ulam-Rassias stabilities for a class of nonlinear integro-differential equations. In [10], Benchohra and Bouriahi investigated existence and stability of solutions for a class of boundary value problem for implicit Caputo fractional differential equations of the type:

$$\begin{aligned} {}^c D^\alpha y(t) &= f(t, y(t), {}^c D^\alpha y(t)), \quad t \in J := [0, T], \quad T > 0, \\ ay(0) + by(T) &= c. \end{aligned}$$

Kucche and Shikhare [27] studied the Ulam-Hyers stabilities for Volterra integro-differential equations and Volterra delay integro-differential equations in Banach spaces on both finite and infinite intervals by using Pachpatte's inequality.

The above results motivates us and therefore, in this paper, we obtain the existence, uniqueness and various types of Ulam stability of the following nonlinear Caputo fractional integro-differential equations of order α ($0 < \alpha \leq 1$) with constant coefficient $\lambda > 0$ of the type:

$$\begin{aligned} {}^c D^\alpha y(t) &= \lambda y(t) + f\left(t, y(t), \int_0^t h(t, s)y(s)ds\right), \quad t \in J := [0, T], \quad T > 0, \quad (1) \\ y(0) + g(y) &= y_0, \quad (2) \end{aligned}$$

where $f : J \times \mathbf{R} \times \mathbf{R} \rightarrow \mathbf{R}$ is a continuous function, $g : C(J, \mathbf{R}) \rightarrow \mathbf{R}$ is a continuous function and y_0 is a real constant. This type of nonlocal Cauchy problem was introduced by Byszewski [12, 13]. The nonlocal condition can be more useful than the classical initial condition to describe some physical

phenomena [12,13] . We take an example of nonlocal conditions as follows:

$$g(y) = \sum_{i=1}^p c_i y(t_i), \tag{3}$$

where $c_i, i = 1, 2, \dots, p$ are constants and $0 < t_1 < \dots < t_p \leq T$.

The rest of the paper is organized as follows. In Section 2, some definitions, notations and basic results are given. Section 3 is devoted to study the existence, uniqueness and stability of the problem (1)-(2). An illustrative example is given in the last section.

2 Preliminaries

In this section, we introduce some definitions, notations and results which are useful for further discussion. For $T > 0$ and $J = [0, T]$, $C(J, \mathbf{R})$ denotes the Banach space of all continuous functions from J into \mathbf{R} with the norm $\|y\|_\infty = \sup\{|y(t)| : t \in J\}$. Also $L^1(J)$ denotes the space of Lebesgue-integrable functions $y : J \rightarrow \mathbf{R}$ with the norm

$$\|y\|_{L^1} = \int_0^T |y(t)| dt.$$

Definition 1. [32] The Riemann-Liouville fractional integral of a function $h \in L^1([0, T], \mathbf{R}_+)$ of order $\alpha \in \mathbf{R}_+$ is defined by

$$I^\alpha h(t) = \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} h(s) ds,$$

where Γ is the Euler gamma function.

Definition 2. [24] The Caputo fractional derivative of order $\alpha > 0$ of a function $h \in L^1([0, T], \mathbf{R}_+)$ is defined as

$${}^c D^\alpha h(t) = \frac{1}{\Gamma(n-\alpha)} \int_0^t (t-s)^{n-\alpha-1} h^{(n)}(s) ds,$$

where $n=[\alpha]+1$ and $[\alpha]$ denotes the integer part of the real number α .

Lemma 1. [24] Let $\alpha > 0$ and $n=[\alpha]+1$. Then

$$I^\alpha ({}^c D^\alpha f(t)) = f(t) - \sum_{k=0}^{n-1} \frac{f^{(k)}(0)}{k!} t^k,$$

where $f^{(k)}(t)$ is the usual derivative of $f(t)$ of order k .

Lemma 2. [32] Let $\alpha > 0$. Then the fractional differential equation

$${}^c D^\alpha h(t) = 0,$$

has the solution $h(t) = c_0 + c_1 t + c_2 t^2 + \dots + c_{n-1} t^{n-1}$, where c_i , $i = 0, 1, 2, \dots, n-1$ are constants and $n = [\alpha] + 1$.

The following Pachpatte's inequality plays an important role in obtaining our main results.

Theorem 1. ([31, page 39]) Let $u(t)$, $f(t)$ and $q(t)$ be nonnegative continuous functions defined on \mathbf{R}_+ , and $n(t)$ be a positive and nondecreasing continuous function defined on \mathbf{R}_+ for which the inequality

$$u(t) \leq n(t) + \int_0^t f(s) \left[u(s) + \int_0^s q(\tau) u(\tau) d\tau \right] ds,$$

holds for $t \in \mathbf{R}_+$. Then

$$u(t) \leq n(t) \left[1 + \int_0^t f(s) \exp \left(\int_0^s [f(\tau) + q(\tau)] d\tau \right) ds \right],$$

for $t \in \mathbf{R}_+$.

The following definitions are useful in the study of stability results.

Definition 3. [10, 36] The equation (1) is Ulam-Hyers stable if there exists a real number $c_f > 0$ such that for each $\epsilon > 0$ and for each solution $z \in C^1(J, \mathbf{R})$ of the inequality

$$\left\| {}^c D^\alpha z(t) - \lambda z(t) - f \left(t, z(t), \int_0^t h(t, s) z(s) ds \right) \right\| \leq \epsilon, \quad t \in J,$$

there exists a solution $y \in C^1(J, \mathbf{R})$ of equation (1) with $\|z(t) - y(t)\| \leq c_f \epsilon$, $t \in J$.

Definition 4. [10, 36] The equation (1) is generalized Ulam-Hyers stable if there exists $\psi_f \in C(\mathbf{R}_+, \mathbf{R}_+)$, $\psi_f(0) = 0$, such that for each solution $z \in C^1(J, \mathbf{R})$ of the inequality

$$\left\| {}^c D^\alpha z(t) - \lambda z(t) - f \left(t, z(t), \int_0^t h(t, s) z(s) ds \right) \right\| \leq \epsilon, \quad t \in J,$$

there exists a solution $y \in C^1(J, \mathbf{R})$ of equation (1) with

$$\|z(t) - y(t)\| \leq \psi_f(\epsilon), \quad t \in J.$$

Definition 5. [10, 36] The equation (1) is Ulam-Hyers-Rassias stable with respect to $\varphi \in C(J, \mathbf{R}_+)$ if there exists a real number $c_f > 0$ such that for each $\epsilon > 0$ and for each solution $z \in C^1(J, \mathbf{R})$ of the inequality

$$\left\| {}^c D^\alpha z(t) - \lambda z(t) - f\left(t, z(t), \int_0^t h(t, s)z(s)ds\right) \right\| \leq \epsilon \varphi(t), \quad t \in J,$$

there exists a solution $y \in C^1(J, \mathbf{R})$ of equation (1) with

$$\|z(t) - y(t)\| \leq c_f \epsilon \varphi(t), \quad t \in J.$$

Definition 6. [10, 36] The equation (1) is generalized Ulam-Hyers-Rassias stable with respect to $\varphi \in C(J, \mathbf{R}_+)$ if there exists a real number $c_{f,\varphi} > 0$ such that for each solution $z \in C^1(J, \mathbf{R})$ of the inequality

$$\left\| {}^c D^\alpha z(t) - \lambda z(t) - f\left(t, z(t), \int_0^t h(t, s)z(s)ds\right) \right\| \leq \varphi(t), \quad t \in J,$$

there exists a solution $y \in C^1(J, \mathbf{R})$ of equation (1) with

$$\|z(t) - y(t)\| \leq c_{f,\varphi} \varphi(t), \quad t \in J.$$

Remark 1. A function $z \in C^1(J, \mathbf{R})$ is a solution of the inequality

$$\left\| {}^c D^\alpha z(t) - \lambda z(t) - f\left(t, z(t), \int_0^t h(t, s)z(s)ds\right) \right\| \leq \epsilon, \quad t \in J,$$

if and only if there exists a function $g \in C(J, \mathbf{R})$ (which depends on solution z) such that

- i) $\|g(t)\| \leq \epsilon, \quad \forall t \in J.$
- ii) ${}^c D^\alpha z(t) = \lambda z(t) + f(t, z(t), \int_0^t h(t, s)z(s)ds) + g(t), \quad t \in J.$

Remark 2. Clearly,

- i): Definition 3. implies Definition 4.
- ii): Definition 5. implies Definition 6.

Remark 3. A solution of the fractional differential inequality

$$\left\| {}^c D^\alpha z(t) - \lambda z(t) - f\left(t, z(t), \int_0^t h(t, s)z(s)ds\right) \right\| \leq \epsilon, \quad t \in J,$$

is called an fractional ϵ -solution of the nonlinear fractional integro-differential equation (1).

3 Existence and Ulam-Hyers stability of the non-local problem

In this section we obtain existence, uniqueness and stability results for the nonlocal problem (1)-(2). Now we introduce the following set of conditions:

(H1) There exists a constant $L > 0$ such that

$$\|f(t, x, y) - f(t, \bar{x}, \bar{y})\| \leq L(\|x - \bar{x}\| + \|y - \bar{y}\|),$$

for each $t \in J$ and $x, y, \bar{x}, \bar{y} \in \mathbf{R}$.

(H2) The function $f : J \times \mathbf{R} \times \mathbf{R} \rightarrow \mathbf{R}$ is continuous.

(H3) There exists a constant $a_f > 0$ such that

$$\|f(t, x, y)\| \leq a_f(1 + \|x\| + \|y\|),$$

for each $t \in J$ and $x, y \in \mathbf{R}$.

(H4) There exists a constant $G > 0$ such that $\|g(y)\| \leq G$, for each $y \in C(J, \mathbf{R})$.

(H5) There exists a constant $\bar{K} > 0$ such that $\|g(y) - g(\bar{y})\| \leq \bar{K} \|y - \bar{y}\|$, for each $y, \bar{y} \in C(J, \mathbf{R})$.

Lemma 3. [10] *Let $0 < \alpha \leq 1$ and $h : [0, T] \rightarrow \mathbf{R}$ be a continuous function. Then the linear problem*

$$\begin{aligned} {}^c D^\alpha y(t) &= h(t), \quad t \in [0, T], \quad T > 0, \\ y(0) + g(y) &= y_0, \end{aligned}$$

has a unique solution which is given by

$$y(t) = y_0 - g(y) + \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} h(s) ds.$$

As a consequence of Lemma 3 and [23], we have the following result which is useful in our main results.

Lemma 4. *Let $f : J \times \mathbf{R} \times \mathbf{R} \rightarrow \mathbf{R}$ be a continuous function. Then the problem (1)-(2) is equivalent to the following integral equation*

$$\begin{aligned} y(t) &= y_0 - g(y) + \frac{\lambda}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} y(s) ds \\ &\quad + \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} f\left(s, y(s), \int_0^s h(t, \tau) y(\tau) d\tau\right) ds, \quad t \in J. \quad (4) \end{aligned}$$

Theorem 2. *Assume that (H1), (H2), (H5) hold. If*

$$\left[\bar{K} + \frac{(\lambda + L)T^\alpha + Lh_T T^{\alpha+1}}{\Gamma(\alpha + 1)} \right] < 1, \quad (5)$$

where $h_T = \sup\{|h(t, s)| \mid 0 \leq s \leq t \leq T\}$, then the nonlocal problem (1)-(2) has a unique solution on J .

Proof. We transform problem (1)-(2) into a fixed point problem. For this, consider the operator $\bar{F} : C(J, \mathbf{R}) \rightarrow C(J, \mathbf{R})$ defined by

$$\begin{aligned} \bar{F}(y)(t) = & y_0 - g(y) + \frac{\lambda}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} y(s) ds \\ & + \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} f\left(s, y(s), \int_0^s h(t, \tau) y(\tau) d\tau\right) ds. \end{aligned} \quad (6)$$

Let $x, y \in C(J, \mathbf{R})$. Then for each $t \in J$, we have

$$\begin{aligned} & \|\bar{F}(x)(t) - \bar{F}(y)(t)\| \\ & \leq \|g(x) - g(y)\| + \frac{\lambda}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \|x(s) - y(s)\| ds \\ & \quad + \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \left\| f\left(s, x(s), \int_0^s h(t, \tau) x(\tau) d\tau\right) \right. \\ & \quad \left. - f\left(s, y(s), \int_0^s h(t, \tau) y(\tau) d\tau\right) \right\| ds \\ & \leq \bar{K} \|x(t) - y(t)\| + \frac{\lambda}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} |x(s) - y(s)| ds \\ & \quad + \frac{L}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \left(\|x(s) - y(s)\| + \int_0^s |h(s, \tau)| \|x(\tau) - y(\tau)\| d\tau \right) ds \\ & \leq \bar{K} \|x(t) - y(t)\| + \frac{(\lambda + L)}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \|x(s) - y(s)\| ds \\ & \quad + \frac{Lh_T T}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \|x(\tau) - y(\tau)\| ds \\ & \leq \left[\bar{K} + \frac{(\lambda + L)T^\alpha + Lh_T T^{\alpha+1}}{\Gamma(\alpha + 1)} \right] \|x - y\|_\infty. \end{aligned}$$

Thus

$$\|\bar{F}(x) - \bar{F}(y)\|_\infty \leq \left[\bar{K} + \frac{(\lambda + L)T^\alpha + Lh_T T^{\alpha+1}}{\Gamma(\alpha + 1)} \right] \|x - y\|_\infty.$$

This implies that \bar{F} is a contraction due to the inequality (5). By Banach contraction principle, we deduce that \bar{F} has a unique fixed point which is a solution of the problem (1)-(2). \square

The next result is based on Schaefer's fixed point theorem.

Theorem 3. *Assume that (H2), (H3), (H4) hold. Then the nonlocal problem (1)-(2) has at least one solution on J .*

Proof. We complete the proof in the following four steps.

Step 1: \bar{F} is continuous.

Let $\{y_n\}$ be a sequence such that $y_n \rightarrow y$ in $C(J, \mathbf{R})$. Then for each $t \in J$, we have

$$\begin{aligned} & \|\bar{F}(y_n)(t) - \bar{F}(y)(t)\| \\ & \leq \|g(y_n) - g(y)\| + \frac{\lambda}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \|y_n(s) - y(s)\| ds \\ & \quad + \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \sup_{t \in J} \left\| f\left(s, y_n(s), \int_0^s h(t, \tau) y_n(\tau) d\tau\right) \right. \\ & \quad \left. - f\left(s, y(s), \int_0^s h(t, \tau) y(\tau) d\tau\right) \right\| ds. \end{aligned}$$

Since f and g are continuous functions and $y_n \rightarrow y$, then we have

$$\|\bar{F}(y_n)(t) - \bar{F}(y)(t)\|_{\infty} \rightarrow 0,$$

as $n \rightarrow \infty$. Consequently, \bar{F} is continuous.

Step 2: \bar{F} maps bounded sets into bounded sets in $C(J, \mathbf{R})$.

We need to show that for any $\eta^* > 0$, there exists a positive constant l such that for each $y \in B_{\eta^*} = \{y \in C(J, \mathbf{R}) : \|y\|_{\infty} \leq \eta^*\}$, we have $\|\bar{F}(y)\|_{\infty} \leq l$. By (H3) and (H4), for each $t \in J$, we have

$$\begin{aligned} \|\bar{F}(y)(t)\| & \leq \|y_0\| + \|g(y)\| + \frac{\lambda}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \|y(s)\| ds \\ & \quad + \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \left\| f\left(s, y(s), \int_0^s h(t, \tau) y(\tau) d\tau\right) \right\| ds \\ & \leq \|y_0\| + G + \frac{\lambda \eta^* T^{\alpha}}{\Gamma(\alpha+1)} \\ & \quad + \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} a_f (1 + \|y(s)\| + \int_0^s |h(t, \tau)| \|y(\tau)\| d\tau) ds \\ & \leq \|y_0\| + G + \frac{\lambda \eta^* T^{\alpha}}{\Gamma(\alpha+1)} + \frac{a_f (1 + \eta^* + h_T \eta^* T) T^{\alpha}}{\Gamma(\alpha+1)}. \end{aligned}$$

Thus

$$\|\bar{F}(y)\|_{\infty} \leq \|y_0\| + G + \frac{\lambda \eta^* T^{\alpha}}{\Gamma(\alpha+1)} + \frac{a_f (1 + \eta^* + h_T \eta^* T) T^{\alpha}}{\Gamma(\alpha+1)} := l.$$

Step 3: \bar{F} maps bounded sets into equicontinuous sets of $C(J, \mathbf{R})$.

Let $t_1, t_2 \in (0, T]$, $t_1 < t_2$, B_{η^*} be a bounded set of $C(J, \mathbf{R})$ as in step 2, and let $y \in B_{\eta^*}$. Then

$$\begin{aligned} & \|\bar{F}(y)(t_1) - \bar{F}(y)(t_2)\| \\ & \leq \frac{\lambda}{\Gamma(\alpha)} \int_0^{t_1} \{(t_1 - s)^{\alpha-1} - (t_2 - s)^{\alpha-1}\} \|y(s)\| ds \\ & \quad + \frac{1}{\Gamma(\alpha)} \int_0^{t_1} \{(t_1 - s)^{\alpha-1} - (t_2 - s)^{\alpha-1}\} \left\| f\left(s, y(s), \int_0^s h(t, \tau)y(\tau)d\tau\right) \right\| ds \\ & \quad + \frac{\lambda}{\Gamma(\alpha)} \int_{t_1}^{t_2} (t_2 - s)^{\alpha-1} \|y(s)\| ds \\ & \quad + \frac{1}{\Gamma(\alpha)} \int_{t_1}^{t_2} (t_2 - s)^{\alpha-1} \left\| f\left(s, y(s), \int_0^s h(t, \tau)y(\tau)d\tau\right) \right\| ds \\ & \leq \frac{\lambda\eta^*}{\Gamma(\alpha)} \int_0^{t_1} \{(t_1 - s)^{\alpha-1} - (t_2 - s)^{\alpha-1}\} ds \\ & \quad + \frac{a_f(1 + \eta^* + h_T\eta^*T)}{\Gamma(\alpha)} \int_0^{t_1} \{(t_1 - s)^{\alpha-1} - (t_2 - s)^{\alpha-1}\} ds \\ & \quad + \frac{\lambda\eta^*}{\Gamma(\alpha)} \int_{t_1}^{t_2} (t_2 - s)^{\alpha-1} ds + \frac{a_f(1 + \eta^* + h_T\eta^*T)}{\Gamma(\alpha)} \int_{t_1}^{t_2} (t_2 - s)^{\alpha-1} ds \\ & \leq \frac{(\lambda\eta^* + a_f(1 + \eta^* + h_T\eta^*T))}{\Gamma(\alpha + 1)} \{2(t_2 - t_1)^\alpha + (t_1^\alpha - t_2^\alpha)\}. \end{aligned}$$

As $t_1 \rightarrow t_2$, the right-hand side of the above inequality tends to zero. As a consequence of steps 1 to 3 together with the Arzela-Ascoli theorem, we can conclude that $\bar{F} : C(J, \mathbf{R}) \rightarrow C(J, \mathbf{R})$ is continuous and completely continuous.

Step 4: A priori bounds.

Now it remains to show that the set

$$\mathcal{E} = \{y \in C(J, \mathbf{R}) : y = \beta\bar{F}(y), \text{ for some } \beta \in (0, 1)\},$$

is bounded. Let $y \in \mathcal{E}$, then $y = \beta\bar{F}(y)$, for some $\beta \in (0, 1)$. Thus, for each $t \in J$ we have

$$\begin{aligned} y(t) = \beta \left\{ & y_0 - g(y) + \frac{\lambda}{\Gamma(\alpha)} \int_0^t (t - s)^{\alpha-1} y(s) ds \right. \\ & \left. + \frac{1}{\Gamma(\alpha)} \int_0^t (t - s)^{\alpha-1} f\left(s, y(s), \int_0^s h(t, \tau)y(\tau)d\tau\right) ds \right\}. \end{aligned}$$

This implies by (H3) and (H4) that for each $t \in J$ we have

$$\|\bar{F}(y)(t)\| \leq \|y_0\| + G + \frac{\lambda\eta^*T^\alpha}{\Gamma(\alpha+1)} + \frac{a_f(1+\eta^*+h_T\eta^*T)T^\alpha}{\Gamma(\alpha+1)}.$$

Thus for every $t \in J$, we have

$$\|\bar{F}(y)\|_\infty \leq \|y_0\| + G + \frac{\lambda\eta^*T^\alpha}{\Gamma(\alpha+1)} + \frac{a_f(1+\eta^*+h_T\eta^*T)T^\alpha}{\Gamma(\alpha+1)} := R.$$

This shows that the set \mathcal{E} is bounded. Now applying Schaefer's fixed point theorem, we deduce that \bar{F} has a fixed point which is a solution of the problem (1)-(2). \square

Theorem 4. *Assume that (H1), (H5) and the inequality (5) hold. Then the nonlocal problem (1)-(2) is Ulam-Hyers stable.*

Proof. Let $\epsilon > 0$ and let $z \in C^1(J, \mathbf{R})$ be a function which satisfies the inequality

$$\left\| {}^cD^\alpha z(t) - \lambda z(t) - f\left(s, z(s), \int_0^s h(t, \tau)z(\tau)d\tau\right) \right\| \leq \epsilon, \quad (7)$$

for every $t \in J$ and let $y \in C(J, \mathbf{R})$ be the unique solution of the following Cauchy problem

$$\begin{aligned} {}^cD^\alpha y(t) &= \lambda y(t) + f\left(s, y(s), \int_0^s h(t, \tau)y(\tau)d\tau\right), \quad t \in J, \quad 0 < \alpha \leq 1, \\ z(0) + g(y) &= y_0. \end{aligned}$$

By Lemma 4, we have

$$\begin{aligned} y(t) &= y_0 - g(y) + \frac{\lambda}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} y(s) ds \\ &\quad + \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} f\left(s, y(s), \int_0^s h(t, \tau)y(\tau)d\tau\right) ds. \end{aligned}$$

By integrating (7), we obtain

$$\begin{aligned} &\left\| z(t) - y_0 + g(z) - \frac{\lambda}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} z(s) ds \right. \\ &\quad \left. - \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} f\left(s, z(s), \int_0^s h(t, \tau)z(\tau)d\tau\right) ds \right\| \leq \frac{\epsilon t^\alpha}{\Gamma(\alpha+1)}. \quad (8) \end{aligned}$$

Using (H1), (H5) and the inequality (8), for every $t \in J$, we have

$$\begin{aligned} \|z(t) - y(t)\| &\leq \left\| z(t) - y_0 + g(z) - \frac{\lambda}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} z(s) ds \right. \\ &\quad \left. - \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} f\left(s, z(s), \int_0^s h(t, \tau) z(\tau) d\tau\right) ds \right\| \\ &\quad + \|g(z) - g(y)\| + \frac{\lambda}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \|z(s) - y(s)\| ds \\ &\quad + \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \left\| f\left(s, z(s), \int_0^s h(t, \tau) z(\tau) d\tau\right) \right. \\ &\quad \left. - f\left(s, y(s), \int_0^s h(t, \tau) y(\tau) d\tau\right) \right\| ds, \\ &\leq \frac{\epsilon t^\alpha}{\Gamma(\alpha+1)} + \bar{K} \|z(t) - y(t)\| \\ &\quad + \frac{(\lambda+L)}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \|z(s) - y(s)\| ds \\ &\quad + \frac{Lh_T}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \left(\int_0^s \|z(\tau) - y(\tau)\| d\tau \right) ds. \end{aligned}$$

Thus

$$\begin{aligned} \|z(t) - y(t)\| &\leq \frac{\epsilon t^\alpha}{\Gamma(\alpha+1)(1-\bar{K})} \\ &\quad + \frac{(\lambda+L)}{\Gamma(\alpha)(1-\bar{K})} \int_0^t (t-s)^{\alpha-1} \|z(s) - y(s)\| ds \\ &\quad + \frac{Lh_T}{\Gamma(\alpha)(1-\bar{K})} \int_0^t (t-s)^{\alpha-1} \left(\int_0^s \|z(\tau) - y(\tau)\| d\tau \right) ds, \\ &\leq \frac{\epsilon t^\alpha}{\Gamma(\alpha+1)(1-\bar{K})} \\ &\quad + \int_0^t \frac{(\lambda+L)}{\Gamma(\alpha)(1-\bar{K})} (T-s)^{\alpha-1} \left[\|z(s) - y(s)\| \right. \\ &\quad \left. + \int_0^s \frac{Lh_T}{(\lambda+L)} \|z(\tau) - y(\tau)\| d\tau \right] ds. \end{aligned} \tag{9}$$

By applying Pachpatte’s inequality given in Theorem 1 to the inequality (9) with

$$\begin{aligned} u(t) &= \|z(t) - y(t)\|, \quad n(t) = \frac{\epsilon t^\alpha}{\Gamma(\alpha+1)(1-\bar{K})}, \\ f(s) &= \frac{(\lambda+L)}{\Gamma(\alpha)(1-\bar{K})} (T-s)^{\alpha-1}, \quad q(\tau) = \frac{Lh_T}{(\lambda+L)}, \end{aligned}$$

we obtain

$$\begin{aligned} \|z(t) - y(t)\| &\leq \frac{\epsilon t^\alpha}{\Gamma(\alpha+1)(1-\bar{K})} \left[1 + \int_0^T \frac{(\lambda+L)}{\Gamma(\alpha)(1-\bar{K})} (T-s)^{\alpha-1} \right. \\ &\quad \times \exp\left(\int_0^s \left\{ \frac{(\lambda+L)}{\Gamma(\alpha)(1-\bar{K})} (T-\tau)^{\alpha-1} + \frac{Lh_T}{(\lambda+L)} \right\} d\tau\right) ds \Big], \\ &\leq \frac{\epsilon T^\alpha}{\Gamma(\alpha+1)(1-\bar{K})} \left[1 + \int_0^T \frac{(\lambda+L)}{\Gamma(\alpha)(1-\bar{K})} (T-s)^{\alpha-1} \right. \\ &\quad \times \exp\left(\int_0^s \left\{ \frac{(\lambda+L)}{\Gamma(\alpha)(1-\bar{K})} (T-\tau)^{\alpha-1} + \frac{Lh_T}{(\lambda+L)} \right\} d\tau\right) ds \Big]. \end{aligned}$$

Putting

$$\begin{aligned} C &= \frac{T^\alpha}{\Gamma(\alpha+1)(1-\bar{K})} \left[1 + \int_0^T \frac{(\lambda+L)}{\Gamma(\alpha)(1-\bar{K})} (T-s)^{\alpha-1} \right. \\ &\quad \times \exp\left(\int_0^s \left\{ \frac{(\lambda+L)}{\Gamma(\alpha)(1-\bar{K})} (T-\tau)^{\alpha-1} + \frac{Lh_T}{(\lambda+L)} \right\} d\tau\right) ds \Big], \end{aligned}$$

we obtain $\|z(t) - y(t)\| \leq C\epsilon$, $\forall t \in J$. Thus the problem (1)-(2) is Ulam-Hyers stable. \square

Corollary 1. *If f and g in the nonlocal problem (1)-(2) satisfy the conditions (H1), (H5) and the inequality (5) hold, then the nonlocal problem (1)-(2) is generalized Ulam-Hyers stable.*

Theorem 5. *Assume that (H1), (H5) and inequality (5) hold. Further suppose there exist an increasing function $\varphi \in C(J, \mathbf{R}_+)$ and $\kappa_\varphi > 0$ such that $I^\alpha \varphi(t) \leq \kappa_\varphi \varphi(t)$, for any $t \in J$. Then the nonlocal problem (1)-(2) is Ulam-Hyers-Rassias stable.*

Proof. Let $z \in C^1(J, \mathbf{R})$ be a solution of the following inequality

$$\left\| {}^c D^\alpha z(t) - \lambda z(t) - f\left(t, z(t), \int_0^t h(t, \tau) z(\tau) d\tau\right) \right\| \leq \epsilon \varphi(t), \quad (10)$$

for any $t \in J$, $\epsilon > 0$. Let $y \in C(J, \mathbf{R})$ be the unique solution of the following Cauchy problem

$$\begin{aligned} {}^c D^\alpha y(t) &= \lambda y(t) + f\left(t, y(t), \int_0^t h(t, \tau) y(\tau) d\tau\right), \quad t \in J; \quad 0 < \alpha \leq 1, \\ z(0) + g(y) &= y_0. \end{aligned}$$

By Lemma 4, we have

$$\begin{aligned} y(t) &= y_0 - g(y) + \frac{\lambda}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} y(s) ds \\ &\quad + \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} f\left(s, y(s), \int_0^s h(t, \tau) y(\tau) d\tau\right) ds. \end{aligned}$$

By integrating (10), we obtain

$$\begin{aligned} & \left\| z(t) - y_0 + g(z) - \frac{\lambda}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} z(s) ds \right. \\ & \quad \left. - \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} f\left(s, z(s), \int_0^s h(t, \tau) z(\tau) d\tau\right) ds \right\| \\ & \leq \frac{\epsilon}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \varphi(s) ds = \epsilon I^\alpha \varphi(t) \leq \epsilon \kappa_\varphi \varphi(t). \end{aligned} \quad (11)$$

Further for any $t \in J$ we have

$$\begin{aligned} \|z(t) - y(t)\| & \leq \left\| z(t) - y_0 + g(z) - \frac{\lambda}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} z(s) ds \right. \\ & \quad \left. - \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} f\left(s, z(s), \int_0^s h(t, \tau) z(\tau) d\tau\right) ds \right\| \\ & \quad + \|g(z) - g(y)\| + \frac{\lambda}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \|z(s) - y(s)\| ds \\ & \quad + \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \left\| f\left(s, z(s), \int_0^s h(t, \tau) z(\tau) d\tau\right) \right. \\ & \quad \left. - f\left(s, y(s), \int_0^s h(t, \tau) y(\tau) d\tau\right) \right\| ds. \end{aligned}$$

Using inequality (11), conditions (H1) and (H5), we obtain

$$\begin{aligned} \|z(t) - y(t)\| & \leq \epsilon \kappa_\varphi \varphi(t) + \bar{K} |z(t) - y(t)| \\ & \quad + \frac{\lambda}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \|z(s) - y(s)\| ds \\ & \quad + \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} L \left(\|z(s) - y(s)\| \right. \\ & \quad \left. + \int_0^s |h(t, \tau)| \|z(\tau) - y(\tau)\| d\tau \right) ds \\ & \leq \epsilon \kappa_\varphi \varphi(t) + \bar{K} |z(t) - y(t)| \\ & \quad + \frac{(\lambda + L)}{\Gamma(\alpha)} \int_0^t (T-s)^{\alpha-1} \|z(s) - y(s)\| ds \\ & \quad + \frac{Lh_T}{\Gamma(\alpha)} \int_0^t (T-s)^{\alpha-1} \left(\int_0^s \|z(\tau) - y(\tau)\| d\tau \right) ds. \end{aligned}$$

Thus

$$\begin{aligned} \|z(t) - y(t)\| &\leq \frac{\epsilon\kappa_\varphi\varphi(t)}{(1-\bar{K})} + \frac{(\lambda+L)}{\Gamma(\alpha)(1-\bar{K})} \int_0^t (T-s)^{\alpha-1} \|z(s) - y(s)\| ds \\ &\quad + \frac{Lh_T}{\Gamma(\alpha)(1-\bar{K})} \int_0^t (T-s)^{\alpha-1} \left(\int_0^s \|z(\tau) - y(\tau)\| d\tau \right) ds \\ &\leq \frac{\epsilon\kappa_\varphi\varphi(t)}{(1-\bar{K})} + \int_0^t \frac{(\lambda+L)}{\Gamma(\alpha)(1-\bar{K})} (T-s)^{\alpha-1} \left[\|z(s) - y(s)\| \right. \\ &\quad \left. + \int_0^s \frac{Lh_T}{(\lambda+L)} \|z(\tau) - y(\tau)\| d\tau \right] ds. \end{aligned}$$

Now by applying Pachpatte's inequality given in the Theorem 1 with

$$\begin{aligned} u(t) &= \|z(t) - y(t)\|, \quad n(t) = \frac{\epsilon\kappa_\varphi\varphi(t)}{(1-\bar{K})}, \\ f(s) &= \frac{(\lambda+L)}{\Gamma(\alpha)(1-\bar{K})} (T-s)^{\alpha-1}, \quad q(\tau) = \frac{Lh_T}{(\lambda+L)}, \end{aligned}$$

we obtain

$$\begin{aligned} \|z(t) - y(t)\| &\leq \frac{\epsilon\kappa_\varphi\varphi(t)}{(1-\bar{K})} \left[1 + \int_0^t \frac{(\lambda+L)}{\Gamma(\alpha)(1-\bar{K})} (T-s)^{\alpha-1} \right. \\ &\quad \left. \times \exp \left(\int_0^s \left\{ \frac{(\lambda+L)}{\Gamma(\alpha)(1-\bar{K})} (T-\tau)^{\alpha-1} + \frac{Lh_T}{(\lambda+L)} \right\} d\tau \right) ds \right] \\ &\leq \frac{\epsilon\kappa_\varphi\varphi(t)}{(1-\bar{K})} \left[1 + \int_0^T \frac{(\lambda+L)}{\Gamma(\alpha)(1-\bar{K})} (T-s)^{\alpha-1} \right. \\ &\quad \left. \times \exp \left(\int_0^s \left\{ \frac{(\lambda+L)}{\Gamma(\alpha)(1-\bar{K})} (T-\tau)^{\alpha-1} + \frac{Lh_T}{(\lambda+L)} \right\} d\tau \right) ds \right]. \end{aligned}$$

Thus we have $\|z(t) - y(t)\| \leq C\epsilon\varphi(t)$, $\forall t \in J$, where

$$\begin{aligned} C &= \frac{\kappa_\varphi}{(1-\bar{K})} \left[1 + \int_0^T \frac{(\lambda+L)}{\Gamma(\alpha)(1-\bar{K})} (T-s)^{\alpha-1} \right. \\ &\quad \left. \times \exp \left(\int_0^s \left\{ \frac{(\lambda+L)}{\Gamma(\alpha)(1-\bar{K})} (T-\tau)^{\alpha-1} + \frac{Lh_T}{(\lambda+L)} \right\} d\tau \right) ds \right]. \end{aligned}$$

□

Corollary 2. *Under the assumptions of Theorem 5, the nonlocal problem (1)-(2) is generalized Ulam-Hyers-Rassias stable.*

4 Example

In this section, we illustrate our main results with the help of following example.

Consider the nonlocal problem:

$${}^cD^{1/2}y(t) = \frac{1}{10}y(t) + \frac{e^{-t}}{(9 + e^t)} \left[\frac{|y(t)|}{1 + |y(t)|} \right] + \frac{1}{10} \int_0^t \frac{e^{-t}}{(3 + t)^2} y(s) ds, \quad t \in [0, 1], \tag{12}$$

$$y(0) + \sum_{i=1}^n c_i y(t_i) = 1, \tag{13}$$

where $0 < t_1 < \dots < t_n < 1$ and $c_i, i = 1, 2, \dots, n$ are positive constants with

$$\sum_{i=1}^n c_i \leq \frac{1}{5}. \tag{14}$$

Problem (12)-(13) is of the form (1)-(2) with $\alpha = \frac{1}{2}, \lambda = \frac{1}{10}$,

$$f(t, y(t), Hy(t)) = \frac{e^{-t}}{(9 + e^t)} \left[\frac{|y(t)|}{1 + |y(t)|} \right] + \frac{1}{10}Hy(t), \quad t \in [0, 1], \quad y \in [0, \infty),$$

where

$$Hy(t) = \int_0^t \frac{e^{-t}}{(3 + t)^2} y(s) ds.$$

Clearly, the function f is continuous. For each $y, \bar{y} \in \mathbf{R}$ and $t \in [0, 1]$

$$\|f(t, y, Hy(t)) - f(t, \bar{y}, H\bar{y}(t))\| \leq \frac{1}{10} \left[\|y - \bar{y}\| + \|Hy - H\bar{y}\| \right].$$

Also, we have

$$\|g(y) - g(\bar{y})\| \leq \left\| \sum_{i=1}^n c_i y - \sum_{i=1}^n c_i \bar{y} \right\| \leq \sum_{i=1}^n c_i \|y - \bar{y}\| \leq \frac{1}{5} \|y - \bar{y}\|.$$

Hence conditions (H1) and (H5) are satisfied with $L = \frac{1}{10}, \bar{K} = \frac{1}{5}, h_T = \frac{1}{9}$ and $\lambda = \frac{1}{10}$. We have

$$\left[\bar{K} + \frac{(\lambda + L)T^\alpha + Lh_T T^{\alpha+1}}{\Gamma(\alpha + 1)} \right] = \left[\frac{1}{5} + \frac{(\frac{1}{10} + \frac{1}{10}) + \frac{1}{90}}{\Gamma(\frac{3}{2})} \right] = \frac{1}{5} + \frac{19}{45\sqrt{\pi}} < 1.$$

It follows from Theorem 2 that the problem (12)-(13) has a unique solution on $[0,1]$ and by Theorem 4, the problem (12)-(13) is Ulam-Hyers stable.

Acknowledgements

The authors are grateful to the anonymous referees for their valuable comments and suggestions which helped us to improve our results.

References

- [1] S. Abbas, M. Benchohra and G.M. N'Guérékata, *Topics in fractional differential equations*, Springer-Verlag, New York, 2012.
- [2] S. Abbas, M. Benchohra and G.M. N'Guérékata, *Advanced fractional differential and integral equations*, Nova Science Publishers, New York, 2015.
- [3] S. Abbas and M. Benchohra, *On the generalized Ulam-Hyers-Rassias stability for Darboux problem for partial fractional implicit differential equations*, Appl. Math. E-Notes **14** (2014) 20–28.
- [4] R.P. Agarwal, M. Benchohra and S. Hamani, *A survey on existence results for boundary value problems of nonlinear fractional differential equations and inclusions*, Acta Appl. Math. **109** (2010) 973–1033.
- [5] C. Alsina and R. Ger, *On some inequalities and stability results related to the exponential function*, J. Inequal. Appl. **2** (1998) 373–380.
- [6] G.A. Anastassiou, *Advances on fractional inequalities*, Springer, New York, 2011.
- [7] T. Aoki, *On the stability of the linear transformation in Banach spaces*, J. Math. Soc. Japan **2** (1950) 64–66.
- [8] D. Baleanu, K. Diethelm, E. Scalas and J.J. Trujillo, *Fractional calculus models and numerical methods*, World Scientific Publishing, New York, 2012.
- [9] D. Baleanu, Z. Güvenc and J. Machado, *New trends in nanotechnology and fractional calculus applications*, Springer, New York, 2000.
- [10] M. Benchohra and S. Bouriahi, *Existence and stability results for nonlinear boundary value problem for implicit differential equations of fractional order*, Moroccan J. Pure Appl. Anal. **1** (2015) 22–37.
- [11] M. Benchohra, S. Hamani, S. K. Ntouyas, *Boundary value problems for differential equations with fractional order and nonlocal conditions*, Nonlinear Anal. **71**(7-8)(2009) 2391–2396.

- [12] L. Byszewski, *Theorem about existence and uniqueness of continuous solution of nonlocal problem for nonlinear hyperbolic equation*, Appl. Anal. **40** (1991) 173–180.
- [13] L. Byszewski, *Theorems about the existence and uniqueness of solutions of a semilinear evolution nonlocal Cauchy problem*, J. Math. Anal. Appl. **162** (1991) 494–505.
- [14] L.P. Castro and A.M. Simões, *Different types of Hyers-Ulam-Rassias stabilities for a class of integro-differential equations*, Filomat **31** (2017) 5379–5390.
- [15] L.P. Castro and A.M. Simões, *Hyers-Ulam-Rassias stability of nonlinear integral equations through the Bielecki metric*, Math. Meth. Appl. Sci. **41** (2018) 7367–7383.
- [16] Y.J. Cho, T.M. Rassias and R. Saadati, *Stability of functional equations in random normed spaces*, Springer, New York, 2013.
- [17] P. Gavrutai, *A generalization of the Hyers-Ulam-Rassias stability of approximately additive mappings*, J. Math. Anal. Appl. **184** (1994) 431–436.
- [18] D.H. Hyers, *On the stability of the linear functional equation*, Proc. Natl. Acad. Sci. U.S.A. **27** (1941) 222–224.
- [19] S.M. Jung, *On the Hyers-Ulam stability of the functional equations that have the quadratic property*, J. Math. Anal. Appl. **222** (1998) 126–137.
- [20] S.M. Jung, *Hyers-Ulam stability of linear differential equations of first order*, Appl. Math. Lett. **19** (2006) 854–858.
- [21] S. M. Jung, *Hyers-Ulam-Rassias stability of functional equations in nonlinear analysis*, Springer Optimization and Its Applications, **48**, Springer-Verlag, New York, 2011.
- [22] K.W. Jun and H.M. Kim, *On the stability of an n -dimensional quadratic and additive functional equation*, Math. Inequal. Appl. **9** (2006) 153–165.
- [23] S.D. Kendre, T.B. Jagtap and V.V. Kharat, *On nonlinear fractional integro–differential equations with non local condition in Banach spaces*, Nonlinear Anal. Differential Equations. **1** (2013) 129–141.

- [24] A.A. Kilbas, H.M. Srivastava and J.J. Trujillo, *Theory and applications of fractional differential equations*, North-Holland Mathematics studies, Elsevier Science B. V., Amsterdam, 2006.
- [25] A.A. Kilbas and S.A. Marzan, *Nonlinear differential equations with the Caputo fractional derivative in the space of continuously differentiable functions*, *Differential Equations* **41** (2005) 84–89.
- [26] G.H. Kim, *On the stability of functional equations with square-symmetric operation*, *Math. Inequal. Appl.* **17** (2001) 257–266.
- [27] K.D. Kucche and P.U. Shikhare, *Ulam-Hyers stability of integrodifferential equations in Banach spaces via Pachpatte's inequality*, *Asian-Eur. J. Math.* **11** (2018) 1850062.
- [28] K.S. Miller and B. Ross, *An introduction to the fractional calculus and differential equations*, John Wiley, New York, 1993.
- [29] M. Obloza, *Hyers stability of the linear differential equation*, *Rocznik Nauk.-Dydakt. Prace Mat.* **13** (1993) 259–270.
- [30] M.D. Ortigueira, *Fractional calculus for scientists and engineers. Lecture notes in electrical engineering*, 84. Springer, Dordrecht, 2011.
- [31] B. Pachpatte, *Inequalities for differential and integral equations*, Academic Press, New York, 1998.
- [32] I. Podlubny, *Fractional differential equations*, Academic Press, New York, 1999.
- [33] T.M. Rassias, *On the stability of the linear mapping in Banach spaces*, *Proc. Amer. Math. Soc.* **72** (1978) 297–300.
- [34] J.M. Rassias, *Functional equations, difference inequalities and Ulam stability notions*, (F.U.N), Inc., New York, 2010.
- [35] T.M. Rassias and J. Brzdek, *Functional equations in mathematical analysis*, Springer, New York, 2012.
- [36] I.A. Rus, *Ulam stabilities of ordinary differential equations in a Banach space*, *Carpathian J. Math.* **26** (2010) 103–107.
- [37] V.E. Tarasov, *Fractional dynamics: applications of fractional calculus to dynamics of particles, fields and media*, Springer, Heidelberg; Higher Education Press, Beijing, 2010.

- [38] S. Tate and H.T. Dinde, *Some theorems on Cauchy problem for nonlinear fractional differential equations with positive constant coefficient*, *Mediterr. J. Math.* **14** (2017) 1–17.
- [39] S.M. Ulam, *Problems in modern mathematics*, John Wiley and sons, New York, USA, 1940.
- [40] S.M. Ulam, *A collection of mathematical problems*, Interscience, New York, 1960.
- [41] J. Wang, M. Feckan and Y. Zhou, *Ulam’s type stability of impulsive ordinary differential equations*, *J. Math. Anal. Appl.* **395** (2012) 258–264.
- [42] J. Wang, L. Lv and Y. Zhou, *Ulam stability and data dependence for fractional differential equations with Caputo derivative*, *Electron. J. Qual. Theory Differ. Equ.* **63** (2011) 1–10.
- [43] J. Wang and Y. Zhang, *Existence and stability of solutions to nonlinear impulsive differential equations in β -normed spaces*, *Electron. J. Differential Equations* **83** (2014) 1–10.