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# ON SUBALGEBRAS OF AN EVOLUTION ALGEBRA OF A "CHICKEN" POPULATION 

B. A. OMIROV AND U. A. ROZIKOV*


#### Abstract

We consider an evolution algebra which corresponds to a bisexual population with a set of females partitioned into finitely many different types and the males having only one type. For such algebras in terms of its structure constants we calculate right and plenary periods of basis elements. Some results on subalgebras of EACP and ideals on low-dimensional EACP are obtained.


## 1. Introduction

In recent years the non-commutative and non-associative analogies of the classical constructions become interesting in the connection with their applications in many branches of mathematics, biology (population, genetics, etc.) and physics (string theory, quantum field theory, etc.).

An algebraic approach in Genetics consists of the study of various types of genetic algebras (like algebras of free, "self-reproduction" and bisexual populations, Bernstein algebras) [4], [6]. Mendel exploited symbols that are quite algebraically suggestive to express his genetic laws. The evolution of a population comprises a determined change of state in the next generations as a result of reproduction and selection [6],[7].

The main problem for a given algebra of a sex linked population is to carefully examine how the basic algebraic model must be altered in order to compensate for this lack of symmetry in the genetic inheritance

[^0]system. In [2] Etherington began the study of this kind of algebras with the simplest possible case.

Recently in [4] an evolution algebra $\mathcal{B}$ is introduced identifying the coefficients of inheritance of a bisexual population as the structure constants of the algebra. The basic properties of the algebra are studied. Moreover a detailed analysis of a special case of the evolution algebra (of bisexual population in which type " 1 " of females and males have preference) is given. Since the structural constants of the algebra $\mathcal{B}$ are given by two cubic matrices, the study of this algebra is quite difficult. To avoid such difficulties one has to consider an algebra of bisexual population with a simplified form of matrices of structural constants. In [5] a such simplified model of bisexual population is considered and basic properties of corresponding evolution algebra (called evolution algebras of a "chicken" population (CEACP)) are studied. In [8] a notion of chain of EACP is introduced and several examples (time homogenous, time non-homogenous, periodic, etc.) of such chains are given.

In this paper we calculate right and plenary periods for basis elements of EACP and establish that natural basis of any subalgebra of EACP (which is also a EACP) can be extended to a natural basis of whole algebra. Moreover, we describe one-dimensional subalgebras (in ordinary sense) of EACP. Finally, simplicity of low-dimensional EACP is investigated.

## 2. Basic definitions

Following [5] we consider a set $\left\{h_{i}, i=1, \ldots, n\right\}$ (the set of "hen"s) and $r$ (a "rooster").
Definition 2.1. [5] Let $(\mathcal{E}, \cdot)$ be an algebra over a field $K$. If it admits a basis $\left\{h_{1}, \ldots, h_{n}, r\right\}$, such that

$$
\begin{align*}
& h_{i} r=r h_{i}=\sum_{j=1}^{n} a_{i j} h_{j}+b_{i} r,  \tag{2.1}\\
& h_{i} h_{j}=0, \quad i, j=1, \ldots, n ; \quad r r=0
\end{align*}
$$

then this algebra is called an evolution algebra of a "chicken" population (EACP). We call the basis $\left\{h_{1}, \ldots, h_{n}, r\right\}$ a natural basis.

Thus an algebra EACP, $\mathcal{E}$, is defined by a rectangular $n \times(n+1)$ matrix

$$
M=\left(\begin{array}{ccccc}
a_{11} & a_{12} & \ldots & a_{1 n} & b_{1} \\
a_{21} & a_{22} & \ldots & a_{2 n} & b_{2} \\
\vdots & \vdots & \ldots & \vdots & \vdots \\
a_{n 1} & a_{n 2} & \ldots & a_{n n} & b_{n}
\end{array}\right)
$$

which is called the matrix of structural constants of the algebra $\mathcal{E}$.
Write the matrix $M$ in the form $M=A \oplus \mathbf{b}$ where $A=\left(a_{i j}\right)_{i, j=1, \ldots, n}$ and $\mathbf{b}^{T}=\left(b_{1}, \ldots, b_{n}\right)$.

Assume we have two rectangular $n \times(n+1)$-matrices $M=A \oplus \mathbf{b}$ and $H=B \oplus \mathbf{c}$. Then we define multiplication of such matrices by

$$
\begin{equation*}
M H=A B \oplus A \mathbf{c}, \quad H M=B A \oplus B \mathbf{b} \tag{2.2}
\end{equation*}
$$

We note that this multiplication agrees with usual multiplication of $(n+1) \times(n+1)$-matrices with zero $(n+1)$-th row.

Let $E$ be a commutative algebra, define principal power of $a \in E$ as

$$
a^{2}=a \cdot a, \quad a^{3}=a^{2} \cdot a, \quad \ldots, \quad a^{n}=a^{n-1} \cdot a ;
$$

and plenary powers of $a$ as

$$
a^{[1]}=a \cdot a, \quad a^{[n]}=a^{[n-1]} a^{[n-1]}, \quad n \geq 2 .
$$

Define right multiplication operator by

$$
R_{a}(x)=x a .
$$

Let $\mathcal{E}$ be an EACP with the basis set $\left\{h_{1}, h_{2}, \ldots, h_{n}, r\right\}$. We say $h_{i}$ (or $r$ ) occurs in $x \in \mathcal{E}$ if the coefficient $\alpha_{i}$ (or $a$ ) in $x=\sum_{i=1}^{n} \alpha_{i} h_{i}+a r$ is non-zero. Write $h_{i} \prec x(r \prec x)$.

Definition 2.2. Let $h_{j}$ be a basis element of an EACP, the right period $p_{j}$ of $h_{j}$ is defined by

$$
p_{j}=\min \left\{m \in N: h_{j} \prec R_{r}^{m}\left(h_{j}\right)\right\} .
$$

If $p_{j}=1$, we say $h_{j}$ is aperiodic; if the set $\left\{m \in N: h_{j} \prec R_{r}^{m}\left(h_{j}\right)\right\}$ is empty we define $p_{j}=\infty$.

Definition 2.3. Let $h_{j}$ be a basis element of an EACP, the plenary period $q_{j}$ of $h_{j}$ is defined by

$$
q_{j}=\min \left\{m \in N: h_{j} \prec\left(h_{j} r\right)^{[m]}\right\} .
$$

If $q_{j}=1$, we say $h_{j}$ is aperiodic; if the set $\left\{m \in N: h_{j} \prec\left(h_{j} r\right)^{[m]}\right\}$ is empty we define $q_{j}=\infty$.

## 3. Conditions of periodicity

Proposition 3.1. For any $m \geq 1$ and for any $i=1, \ldots, n$ the following identities hold
(i) $R_{r}^{m}\left(h_{i}\right)=\left(A^{m} \mathbf{h}\right)_{i}+\left(A^{m-1} \mathbf{b}\right)_{i} r$;
(ii) $\left(h_{i} r\right)^{[m]}=\gamma_{m}\left[\left(A^{m+1} \mathbf{h}\right)_{i}+\left(A^{m} \mathbf{b}\right)_{i} r\right]$, where $\mathbf{h}=\left\{h_{1}, \ldots, h_{n}\right\}$ and $\gamma_{m}$ satisfies the recurrent equation:

$$
\gamma_{m+1}=2 \gamma_{m}^{2}\left(A^{m} \mathbf{b}\right)_{i}, \quad \text { with } \quad \gamma_{1}=2 b_{i} .
$$

Proof. (i) Compute actions of $R_{r}$ to the set $\mathbf{h}$ :
$R_{r}(\mathbf{h})=\left\{R_{r}\left(h_{1}\right), \ldots, R_{r}\left(h_{n}\right)\right\}=\left\{h_{1} r, \ldots, h_{n} r\right\}=\left\{(M \mathbf{h})_{1}, \ldots,(M \mathbf{h})_{n}\right\}$, where

$$
(M \mathbf{h})_{i}=\sum_{j=1}^{n} a_{i j} h_{j}+b_{i} r=(A \mathbf{h})_{i}+b_{i} r, \quad i=1, \ldots, n
$$

Also we have
$R_{r}^{2}\left(h_{i}\right)=R_{r}\left((M \mathbf{h})_{i}\right)=\sum_{s=1}^{n} \sum_{j=1}^{n} a_{i j} a_{j s} h_{s}+\sum_{j=1}^{n} a_{i j} b_{j} r=\left(A^{2} \mathbf{h}\right)_{i}+(A \mathbf{b})_{i} r$.
Using induction by $m$ we get

$$
R_{r}^{m}(\mathbf{h})=\left\{\left(M^{m} \mathbf{h}\right)_{1}, \ldots,\left(M^{m} \mathbf{h}\right)_{n}\right\},
$$

where

$$
\left(M^{m} \mathbf{h}\right)_{i}=R_{r}^{m}\left(h_{i}\right)=\left(A^{m} \mathbf{h}\right)_{i}+\left(A^{m-1} \mathbf{b}\right)_{i} r, \quad i=1, \ldots, n .
$$

(ii) Use induction by $m \geq 1$. For $m=1$ we have

$$
\left(h_{i} r\right)^{[1]}=\left(\sum_{j=1}^{n} a_{i j} h_{j}+b_{i} r\right)^{2}=2 b_{i}\left[\left(A^{2} \mathbf{h}\right)_{i}+(A \mathbf{b})_{i} r\right] .
$$

Assume now that the formula (ii) is true for $m$ and prove it for $m+1$ :

$$
\begin{align*}
\left(h_{i} r\right)^{[m+1]} & =\left(\gamma_{m}\left[\left(A^{m+1} \mathbf{h}\right)_{i}+\left(A^{m} \mathbf{b}\right)_{i} r\right]\right)^{2} \\
= & 2 \gamma_{m}^{2}\left(A^{m} \mathbf{b}\right)_{i}\left(\left(A^{m+1} \mathbf{h}\right)_{i} r\right) . \tag{3.1}
\end{align*}
$$

Let $A^{m}=\left(a_{i j}^{(m)}\right)_{i j=1, \ldots, n}$. Then from (3.1) we get

$$
\begin{align*}
& \left(h_{i} r\right)^{[m+1]}=2 \gamma_{m}^{2}\left(A^{m} \mathbf{b}\right)_{i}\left(\sum_{j=1}^{n} a_{i j}^{(m+1)} h_{j} r\right) \\
& \quad=\gamma_{m+1}\left[\left(A^{m+2} \mathbf{h}\right)_{i}+\left(A^{m+1} \mathbf{b}\right)_{i} r\right] . \tag{3.2}
\end{align*}
$$

As a corollary of this proposition we have
Proposition 3.2. 1) The right period of $h_{i}$ is

$$
p_{i}=\min \left\{m \in N: a_{i i}^{(m)} \neq 0\right\} .
$$

2) If $b_{i}=0$ then $q_{i}=\infty$, otherwise the plenary period of $h_{i}$ is

$$
q_{i}=\min \left\{m \in N: a_{i i}^{(m+1)} \prod_{j=0}^{m-1}\left(A^{j} \mathbf{b}\right)_{i} \neq 0\right\}
$$

where $A^{0}=i d$.

Proof. 1) This simply follows from the part (i) of Proposition 3.1.
2) Using part (ii) of Proposition 3.1 we get

$$
\left(h_{i} r\right)^{[m]}=2^{2^{m}-1} \prod_{j=0}^{m-1}\left(A^{j} \mathbf{b}\right)_{i}^{2^{m-j-1}}\left[\left(A^{m+1} \mathbf{h}\right)_{i}+\left(A^{m} \mathbf{b}\right)_{i} r\right]
$$

Thus the coefficient of $h_{i}$ is

$$
2^{2^{m}-1} \prod_{j=0}^{m-1}\left(A^{j} \mathbf{b}\right)_{i}^{2^{m-j-1}} a_{i i}^{(m+1)}
$$

This completes the proof.
The following proposition reduces an EACP to a simple one.
Proposition 3.3. [1] Let $\mathcal{C}$ be an EACP, then there exists a basis $\left\{h_{1}, h_{2}, \ldots, h_{n}, r\right\}$ such that $\mathcal{C}$ on this basis is represented by the table of multiplication as follows

$$
h_{1} r=\sum_{j=1}^{n} a_{1 j} h_{j}+\delta r, \delta \in\{0,1\}, \quad h_{i} r=\sum_{j=1}^{n} a_{i j} h_{j}, \quad 2 \leq i \leq n .
$$

Using this proposition by Proposition 3.2 we get
Corollary 3.4. For EACP mentioned in Proposition 3.3 the following hold
a) If $\delta=0$ then $q_{i}=1$ or $\infty$,
b) If $\delta=1$ then the plenary period of $h_{i}$ is

$$
q_{i} \in \begin{cases}\{1,2, \infty\} & \text { if } i=1 \\ \{1, \infty\}, & \text { if } i \neq 1\end{cases}
$$

Proof. a) If $h_{i}$ is present in $h_{i} r$ then $q_{i}=1$, otherwise since $\left(h_{i} r\right)^{[m]}=0$ for all $m \geq 2$ we get $q_{i}=\infty$.
b) Case $i=1$. If $h_{1}$ is present in $h_{1} r$ then $q_{1}=1$, otherwise consider $\left(h_{1} r\right)^{[2]}$ if this contains $h_{1}$ then $q_{1}=2$, if $\left(h_{1} r\right)^{[2]}$ does not contain $h_{1}$ then since $\left(h_{1} r\right)^{[m]}=0$ for all $m \geq 3$ we get $q_{i}=\infty$.

Case $i \neq 1$ is similar to part a).

## 4. Subalgebras of an EACP

By definition of an EACP we know that this algebra depends on a natural basis $\left\{h_{1}, h_{2}, \ldots, h_{n}, r\right\}$.

Definition 4.1. [5]

1) Let $\mathcal{C}$ be an EACP and $\mathcal{C}_{1}$ be a subspace of $\mathcal{C}$. If $\mathcal{C}_{1}$ has a natural basis $\left\{h_{1}^{\prime}, h_{2}^{\prime}, \ldots, h_{m}^{\prime}, r^{\prime}\right\}$ with multiplication table like (2.1), then we call $\mathcal{C}_{1}$ an evolution subalgebra of a CP.
2) Let $I \subset \mathcal{C}$ be an evolution subalgebra of a CP . If $\mathcal{C} I \subseteq I$, we call $I$ an evolution ideal of a CP.
3) Let $\mathcal{C}$ and $\mathcal{D}$ be EACPs, we say a linear homomorphism $f$ from $\mathcal{C}$ to $\mathcal{D}$ is an evolution homomorphism, if $f$ is an algebraic map and for a natural basis $\left\{h_{1}, \ldots, h_{n}, r\right\}$ of $\mathcal{C},\left\{f\left(h_{1}\right), \ldots, f\left(h_{n}\right), f(r)\right\}$ spans an evolution subalgebra of a CP in $\mathcal{D}$. Furthermore, if an evolution homomorphism is one to one and onto, it is an evolution isomorphism.
4) An EACP $\mathcal{C}$ is called simple if it has no proper evolution ideals.
5) $\mathcal{C}$ is called irreducible if it has no proper subalgebras.

In fact, for linear subspace $\mathcal{C}_{1}$ of an EACP $\mathcal{C}$ we can consider three type of subalgebras:
(i) $\mathcal{C}_{1}$ is a subalgebra in ordinary sense;
(ii) $\mathcal{C}_{1}$ is subalgebra and there exists a natural basis of $\mathcal{C}_{1}$;
(iii) $\mathcal{C}_{1}$ is subalgebra and there exist a natural basis of $\mathcal{C}_{1}$ which can be extended to a natural basis of $\mathcal{C}$.

Note that Definition 4.1 agrees with the second type of subalgebra.
The following proposition gives equivalence of (ii) and (iii).
Proposition 4.2. Definitions (ii) and (iii) are equivalent.
Proof. Part $(i i i) \Rightarrow(i i)$ is straightforward. We shall prove $(i i) \Rightarrow(i i i)$. Let $\mathcal{C}_{1}=\left\langle f_{1}, f_{2}, \ldots, f_{m}, r^{\prime}\right\rangle$ be a subalgebra of $\mathcal{C}=\left\langle h_{1}, \ldots, h_{n}, r\right\rangle$ in sense (ii). We shall show that the natural basis of $\mathcal{C}_{1}$ can be extended to a natural basis of $\mathcal{C}$. We have

$$
\begin{align*}
f_{i} & =\sum_{j=1}^{n} \alpha_{i j} h_{j}+\gamma_{i} r, \quad i=1, \ldots, m \\
r^{\prime} & =\sum_{j=1}^{n} \beta_{j} h_{j}+\gamma r \tag{4.1}
\end{align*}
$$

Case $\gamma \neq 0$. Take the following change of the basis

$$
f_{i}^{\prime}=f_{i}-\frac{\gamma_{i}}{\gamma} r^{\prime}, \quad 1 \leq i \leq m, \quad r^{\prime \prime}=r^{\prime}
$$

This new basis also is a natural basis, moreover the vectors $f_{i}^{\prime}$ do not contain $r$ in their decompositions. Thus vectors $\left\{f_{1}^{\prime}, \ldots, f_{m}^{\prime}\right\}$ generate a subspace in the vector space generated by $\left\{h_{1}, \ldots, h_{n}\right\}$. Then using theorem about change of basis (see [10]) we can replace $\left\{h_{i_{1}}, \ldots, h_{i_{m}}\right\}$ by $\left\{f_{1}^{\prime}, \ldots, f_{m}^{\prime}\right\}$. Moreover $r$ can be replaced by $r^{\prime}$. Hence for $\gamma \neq 0$ we can extend the natural basis of $\mathcal{C}_{1}$ to the natural basis of $\mathcal{C}$.

Case $\gamma=0$ and $\gamma_{i}=0$ for all $i$. In this case all $f_{i}$ and $r^{\prime}$ do not depend on $r$. So we can again use theorem about change of basis and replace $\left\{h_{i_{1}}, \ldots, h_{i_{m}}, h_{i_{m+1}}\right\}$ by $\left\{f_{1}, \ldots, f_{m}, r^{\prime}\right\}$.

Case $\gamma=0$ and $\gamma_{i} \neq 0$ for some $i$. By change $X_{i}=r^{\prime} ; X_{j}=f_{j}, j \neq$ $i ; r^{\prime \prime}=f_{i}$ we reduce this case to the first case. This completes the proof.

The following is an example of a subalgebra (as in (i)) of $\mathcal{C}$, which is not an evolution subalgebra of a CP (as in (ii)).

Example 4.3. [5] Let $\mathcal{C}$ be an EACP over a field $\mathbb{K}$ with basis $\left\{h_{1}, h_{2}, h_{3}, r\right\}$ and multiplication defined by $h_{i} r=h_{i}+r, i=1,2,3$. Take $u_{1}=h_{1}+r$, $u_{2}=h_{2}+r$. Then

$$
\begin{gathered}
\left(a u_{1}+b u_{2}\right)\left(c u_{1}+d u_{2}\right)=a c u_{1}^{2}+(a d+b c) u_{1} u_{2}+b d u_{2}^{2} \\
=(2 a c+a d+b c) u_{1}+(2 b d+a d+b c) u_{2} .
\end{gathered}
$$

Hence, $F=\mathbb{K} u_{1}+\mathbb{K} u_{2}$ is a subalgebra of $\mathcal{C}$, but it is not an evolution subalgebra of a CP. Indeed, assume $v_{1}, v_{2}$ be a basis of $F$. Then $v_{1}=$ $a u_{1}+b u_{2}$ and $v_{2}=c u_{1}+d u_{2}$ for some $a, b, c, d \in \mathbb{K}$ such that $D=$ $a d-b c \neq 0$. We have $v_{1}^{2}=\left(2 a^{2}+2 a b\right) u_{1}+\left(2 b^{2}+2 a b\right) u_{2}$ and $v_{2}^{2}=$ $\left(2 c^{2}+2 c d\right) u_{1}+\left(2 d^{2}+2 c d\right) u_{2}$. We must have $v_{1}^{2}=v_{2}^{2}=0$, i.e.

$$
a^{2}+a b=0, \quad b^{2}+a b=0, \quad c^{2}+c d=0, \quad d^{2}+c d=0 .
$$

From this we get $a=-b$ and $c=-d$. Then $D=0$, a contradiction. If $a=0$ then $b=0$ (resp. $c=0$ then $d=0$ ), we reach the same contradiction. Hence $v_{1}^{2} \neq 0$ and $v_{2}^{2} \neq 0$, and consequently $F$ is not an evolution subalgebra of a CP.

In sequel for a subalgebra we mean a subalgebra in the sense (iii).
Proposition 4.4. Let $\mathcal{C}$ be an EACP over $\mathbb{R}$ with basis $\left\{h_{1}, \ldots, h_{n}, r\right\}$ and matrix of structural constants $M=A \oplus \mathbf{b}$. If $\operatorname{rank} A=n$, then any subalgebra of $\mathcal{C}$ has the form $\left\langle f_{1}, \ldots, f_{m}\right.$, ar $\rangle$, where $0 \leq m \leq n$, $a \in\{0,1\}$ and

$$
f_{i}=\sum_{j=1}^{n} \alpha_{i j} h_{j}, \quad \alpha_{i j} \in \mathbb{R}, i=1, \ldots, m
$$

Proof. Let $\tilde{\mathcal{C}}=\left\langle\varphi_{1}, \ldots, \varphi_{m}\right\rangle$ be a subalgebra of $\mathcal{C}$. Then we have

$$
\varphi_{i}=\sum_{k=1}^{n} \beta_{i k} h_{k}+\beta_{i} r, \quad i=1, \ldots, m
$$

Since $\varphi_{i}^{2}=0$, then we have

$$
\begin{equation*}
2 \beta_{i} \sum_{k=1}^{n} \beta_{i k} h_{k} r=2 \beta_{i}\left(\sum_{k=1}^{n} \sum_{s=1}^{n} \beta_{i k} a_{k s} h_{s}+\sum_{k=1}^{n} \beta_{i k} b_{k} r\right)=0 . \tag{4.2}
\end{equation*}
$$

Hence $\beta_{i}=0$ or

$$
\begin{equation*}
\sum_{k=1}^{n} \beta_{i k} a_{k s}=0 \text { for any } s \text { and } \sum_{k=1}^{n} \beta_{i k} b_{k}=0 \tag{4.3}
\end{equation*}
$$

Since $\operatorname{rank} A=n$ from (4.3) we get $\beta_{i k}=0$ for all $k$. Hence $\varphi_{i}$ is equal to $\beta_{i} r$ or to $\sum_{k=1}^{n} \beta_{i k} h_{k}$. This completes the proof.

Proposition 4.5. Let $\mathcal{C}$ be an $E A C P$ with matrix of structural constants $M=A \oplus \mathbf{b}$. Then $\mathcal{X}=\langle x\rangle$, where $0 \neq x=y+\beta r=$ $\sum_{i=1}^{n} \alpha_{i} h_{i}+\beta r$ generates an one-dimensional subalgebra if one of the following conditions is satisfied
a. $\beta=0$ or $A y=0, \mathbf{b} y=0$.
b. $\beta \neq 0, \mathbf{b} y=1$ and $y$ is an eigenvector of $A$ with eigenvalue $1 / \beta$.

Proof. An arbitrary $x=\sum_{i=1}^{n} \alpha_{i} h_{i}+\beta r$ generates a subalgebra iff $x^{2}=c x$ for some $c$. Here one can consider only the case $c=0$ and $c=1$. Thus $x$ generates a subalgebra iff it is an absolute nilpotent or idempotent of $\mathcal{C}$. Now the proof follows from Propositions 3.4 and 3.5 of [5].

Proposition 4.6. Let $\mathcal{C}$ be an $E A C P$ as in Proposition 3.3, $\delta=1$ and with matrix of structural constants $M=A \oplus \mathbf{b}$. Then $\mathcal{X}=\langle x\rangle$, where $x=\sum_{i=1}^{n} \alpha_{i} h_{i}+\beta r$ generates an one-dimensional ideal iff one of the following conditions is satisfied
a. $\beta=\alpha_{1}=\sum_{i=2}^{n} a_{i 1} \alpha_{i}=0$ and $x$ (with $\alpha_{1}=0$ ) is an eigenvector of $A_{1}$ with a real eigenvalue, where $A_{1}=\left(a_{i j}\right)_{i, j=2, \ldots, n}$ is the minor of the matrix $A$.
b. $\beta=1$ and $\alpha_{j}=a_{1 j}$ and $a_{k j}=0$, for all $k=2, \ldots, n, j=$ $1, \ldots, n$.

Proof. Take an arbitrary element $y=\sum_{i=1}^{n} \gamma_{i} h_{i}+\nu r \in \mathcal{C}$ we should have $x y \in \mathcal{X}$, i.e. there exists $c$ such that $x y=c x$. The last equality is equivalent to

$$
\left\{\begin{array}{l}
\sum_{i=1}^{n}\left(\nu \alpha_{i}+\beta \gamma_{i}\right) a_{i j}=c \alpha_{j} ; \quad j=1,2, \ldots, n  \tag{4.4}\\
\nu \alpha_{1}+\beta \gamma_{1}=c \beta
\end{array}\right.
$$

a. For case $\beta=0$ if $\nu=0$ then in (4.4) one can take $c=0$. If $\nu \neq 0$ then $\alpha_{1}=0$ and

$$
\begin{aligned}
& \nu \sum_{i=2}^{n} \alpha_{i} a_{i j}=c \alpha_{j} ; \quad j=2, \ldots, n \\
& \sum_{i=2}^{n} \alpha_{i} a_{i 1}=0
\end{aligned}
$$

This completes the proof of a.
b. In the case $\beta \neq 0$ one can take $\beta=1$. For $y=h_{k}, k=2, \ldots, n$ from (4.4) for some $c=c_{k}$ we get the system $a_{k j}=c_{k} \alpha_{j}, j=1, \ldots, n$ and $c_{k}=0$. This implies $a_{k j}=0$ for all $k=2, \ldots, n$ and $j=1, \ldots, n$. In case $y=h_{1}$ we get the system $a_{1 j}=c_{1} \alpha_{j}, j=1, \ldots, n$ and $c_{1}=1$. Hence $a_{1 j}=\alpha_{j}$. Taking into account the above obtained results, for $y=r$ we get $\alpha_{1} a_{1 j}=c \alpha_{j}$ and $\alpha_{1}=c$. Thus we proved that if $A$ has the following form

$$
A=\left(\begin{array}{cccc}
\alpha_{1} & \alpha_{2} & \ldots & \alpha_{n} \\
0 & 0 & \ldots & 0 \\
\vdots & \vdots & \vdots & \vdots \\
0 & 0 & \ldots & 0
\end{array}\right)
$$

then there are $c_{k}$ and $c$ such that $x y=c_{k} x$ if $y=h_{k}$ and $x y=c x$ if $y=r$. Using this result for an arbitrary $y=\sum_{i=1}^{n} \gamma_{i} h_{i}+\nu r \in \mathcal{C}$ we obtain

$$
x y=\sum_{i=1}^{n} \gamma_{i} x h_{i}+\nu x r=\left(\sum_{i=1}^{n} \gamma_{i} c_{i}+c\right) x=C x .
$$

Thus $\mathcal{X}=\left\langle x=\sum_{i=1}^{n} \alpha_{i} h_{i}+r\right\rangle$ is an ideal of the algebra $\mathcal{C}$ with matrix

$$
M=\left(\begin{array}{ccccc}
\alpha_{1} & \alpha_{2} & \ldots & \alpha_{n} & 1 \\
0 & 0 & \ldots & 0 & 0 \\
\vdots & \vdots & \vdots & \vdots & \vdots \\
0 & 0 & \ldots & 0 & 0
\end{array}\right)
$$

## 5. Simple three-dimensional complex EACPs

In the following theorem the classification of three dimensional EACP is presented.
Theorem 5.1. 1. [5] Any 2-dimensional, non-trivial EACP $\mathcal{C}$ is isomorphic to one of the following pairwise non isomorphic algebras:

$$
\mathcal{C}_{1}: \quad r h=h r=h, \quad h^{2}=r^{2}=0
$$

$\mathcal{C}_{2}: \quad r h=h r=\frac{1}{2}(h+r), \quad h^{2}=r^{2}=0$.
2. [1] An arbitrary three dimensional complex EACP $\mathcal{C}$ is isomorphic to one of the following pairwise non-isomorphic algebras

If $\operatorname{dim} \mathcal{C}^{2}=1$ then

$$
\begin{array}{ll}
\mathcal{C}_{1}: & h_{1} r=\frac{1}{2} r \\
\mathcal{C}_{2}: & h_{1} r=\frac{1}{2} h_{2} ; \\
\mathcal{C}_{3}: & h_{1} r=\frac{1}{2} h_{1}+\frac{1}{2} r .
\end{array}
$$

If $\operatorname{dim} \mathcal{C}^{2}=2$ then

$$
\begin{array}{lll}
\mathcal{C}_{4}: & h_{1} r=\frac{1}{2}\left(h_{1}+h_{2}\right), & h_{2} r=\frac{1}{2} h_{2} ; \\
\mathcal{C}_{5}(\beta): & h_{1} r=\frac{1}{2} h_{1}, & h_{2} r=\frac{\beta}{2} h_{2}, \quad \beta \neq 0 ; \\
\mathcal{C}_{6}(\alpha, \beta): & h_{1} r=\frac{1}{2}\left(\alpha h_{1}+\beta h_{2}+r\right), & h_{2} r=\frac{1}{2} h_{1} ; \\
\mathcal{C}_{7}(\alpha): & h_{1} r=\frac{1}{2}\left(\alpha h_{1}+r\right), & h_{2} r=\frac{1}{2} h_{2} ; \\
\mathcal{C}_{8}: & h_{1} r=\frac{1}{2}\left(h_{1}+h_{2}+r\right), & h_{2} r=\frac{1}{2} h_{2} .
\end{array}
$$

where one of non-zero parameter $\alpha, \beta$ in the algebra $\mathcal{C}_{6}(\alpha, \beta)$ can be assumed to be equal to 1 .

The following theorem describes simple and not simple EACP listed in Theorem 5.1.

Theorem 5.2. a. The two-dimensional algebra $\mathcal{C}_{1}$ and $\mathcal{C}_{2}$ are not simple.
b. The three-dimensional algebra $\mathcal{C}_{i}$ is not simple for $i=1,2,3,4,5,7,8$ and $i=6$ for $\beta=0$. Moreover, $\mathcal{C}_{6}(\alpha, \beta)$ is simple for $\beta \neq 0$.

Proof. a. It is easy to see that $\langle h\rangle \triangleleft \mathcal{C}_{1}$ and $\langle h+r\rangle \triangleleft \mathcal{C}_{2}$.
b. Consider some possible subalgebras (in sense (iii)) of $\mathcal{C}=\left\langle h_{1}, h_{2}, r\right\rangle$ :

$$
\begin{gathered}
D_{1}=\left\langle h_{1}\right\rangle, \quad D_{2}=\left\langle h_{1}, h_{2}\right\rangle, \quad D_{3}=\left\langle h_{1}, r\right\rangle, \\
D_{4}=\left\langle h_{2}\right\rangle, \quad D_{5}=\left\langle h_{2}, r\right\rangle, \quad D_{6}=\langle r\rangle .
\end{gathered}
$$

It is easy to check that
$D_{j}=\left\{\begin{array}{l}\text { is ideal for } \mathcal{C}_{1} \text { if } j=3,4,5,6 \text { and is not ideal if } j=1,2 ; \\ \text { is ideal for } \mathcal{C}_{2} \text { if } j=2,4,5 \text { and is not ideal if } j=1,6 ; \\ \text { is ideal for } \mathcal{C}_{3} \text { if } j=3,4 \text { and is not ideal if } j=1,2,5,6 ; \\ \text { is ideal for } \mathcal{C}_{4} \text { if } j=2,4,5 \text { and is not ideal if } j=1,6 ; \\ \text { is ideal for } \mathcal{C}_{5} \text { if } j=1,2,4, \text { and is not ideal if } j=3,5,6 ; \\ \text { is not ideal for } \mathcal{C}_{6} \text { if } j=1,2,4,6 ; \\ \text { is ideal for } \mathcal{C}_{7} \text { if } j=4 \text { and is not ideal if } j=1,2,3,5,6 ; \\ \text { is ideal for } \mathcal{C}_{8} \text { if } j=4 \text { and is not ideal for } j=1,2,5,6 .\end{array}\right.$
Now consider $\mathcal{C}_{6}$ :
Case $\beta=0$. In this case $D_{3}$ will be an ideal, i.e. $\mathcal{C}_{6}(\alpha, 0)$ is not simple.

Case $\beta \neq 0$. This $\beta$ can be reduced to $\beta=1$. We have $\operatorname{rank} A=2$. So we can use Proposition 4.5: consider a general subalgebra $\tilde{\mathcal{C}_{6}}=$ $\left\langle a h_{1}+b h_{2}, \delta r\right\rangle$. For $\delta=0$ it is easy to see that $\tilde{\mathcal{C}}_{6} \mathcal{C}_{6} \not \subset \tilde{\mathcal{C}}_{6}$. If $\delta=1$ then

$$
\tilde{\mathcal{C}}_{6} \mathcal{C}_{6}=\left\langle(a \alpha+b) h_{1}+a h_{2}+a r, \alpha h_{1}+h_{2}+r, h_{1}\right\rangle .
$$

Simple calculations show that $(a \alpha+b) h_{1}+a h_{2}+a r \in \tilde{\mathcal{C}}_{6}$ iff $b=$ $-\frac{a}{2} \cdot\left(\alpha \mp \sqrt{\alpha^{2}+4}\right)$. For this value of $b$ one gets $\alpha h_{1}+h_{2}+r \in \tilde{\mathcal{C}}_{6}$ iff $\alpha \sqrt{\alpha^{2}+4}=\alpha^{2}+2$. But the last equation has not solution. Hence $\mathcal{C}_{6}(\alpha, \beta)$ is simple for any $\beta \neq 0$.

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## B.A. Omirov

Institute of Mathematics, Tashkent, Uzbekistan.
Email: omirovb@mail.ru

## U.A. Rozikov

Institute of Mathematics, Tashkent, Uzbekistan.
Email: rozikovu@yandex.ru


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    $*$ Corresponding author .

